

Motivation

Fast-flowing liquid metal divertors could solve problems imposed on solid components (melting and erosion). However, they suffer severe MHD drag, causing excessive liquid-metal evaporation and possible plasma disruptions.

The injection of an electric current through the liquid metal combined with a transverse magnetic field B , can generate an accelerating force $j \times B$ in the flow direction.

$$t_{cr} = (\Delta T / 2q)^2 \pi k \rho c_p$$

$$\rightarrow t_{cr} \approx 0.03 \pm 0.02 [s]$$

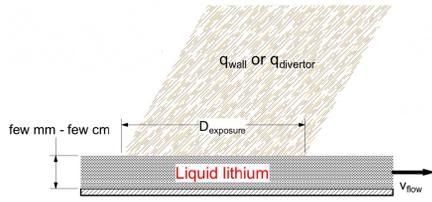
$$\rightarrow u_{cr} \approx 11.5 \pm 4 [m/s]$$


Fig 1. Liquid metal slab [1].

Issues with operation at the reactor scale

- Currents to overcome MHD drag from B_n may require $\sim 10\%$ of power output of DEMO.
- Overcoming drag from toroidal fields \rightarrow larger power requirements.
- Fringing effects of injected currents cause flow detachment from electrodes: unstable flow.

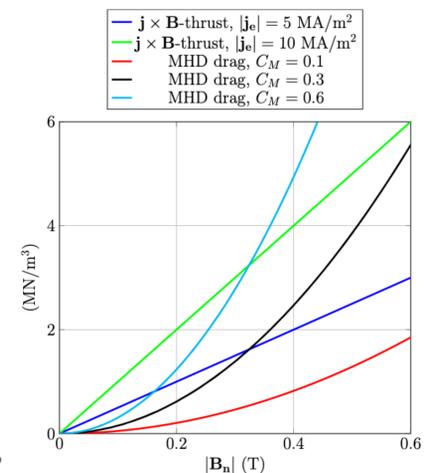


Fig. 5. Power requirements

Acceleration through $j \times B$ thrust

An arrangement of separate chutes (divertor cassettes) with electrodes to apply external currents on liquid metal flows. In combination with magnetic fields, Lorentz-force propulsion is achieved.

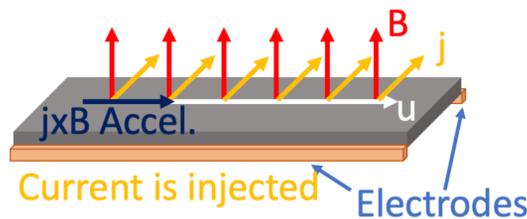


Figure 2. Electrodes for current injection.

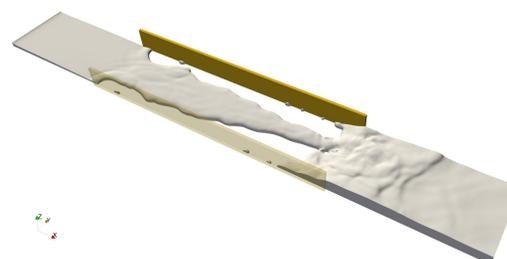
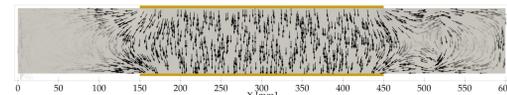


Fig. 6. Fringing effects

Experiments

- LMFREX channel from Kyoto University.
- Tests at the National Institute for Fusion Science (NIFS).
 - B_n normal fields (up to 1.2 T).
 - Electric currents (up to 120 A).
- Galinstan as liquid metal (67% Ga, 20.5% In and 12.5% Sn).
- Laser sheet for local height measurements of liquid metal flow \rightarrow local average speed.

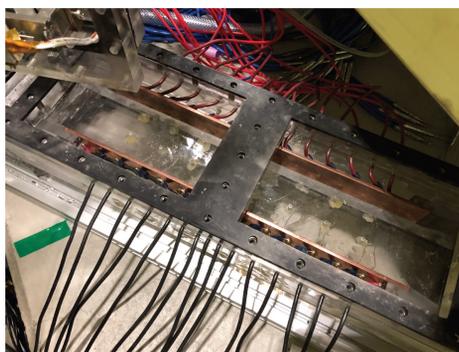
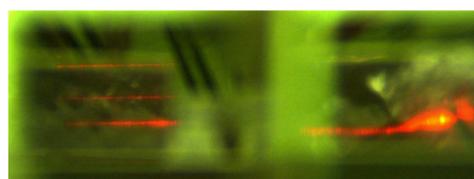
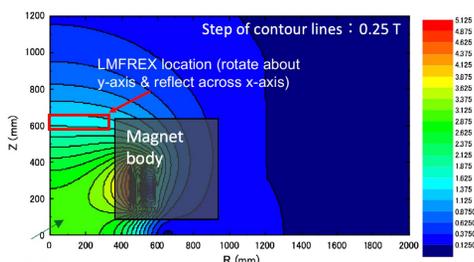
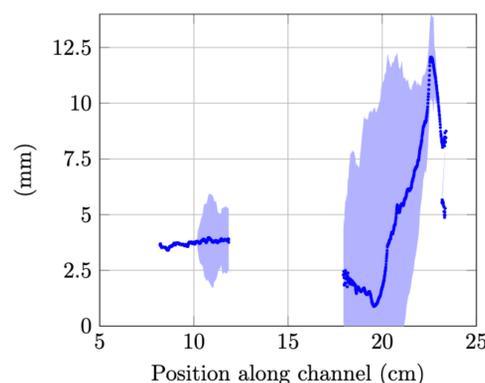


Fig. 3. Experimental setup



Analysis

- 2D Flow, steady state Navier Stokes Equations.
- OpenFOAM simulations.
- Agreement in flow depth and forces.
- Hydraulic jump was observed

$$\nabla \cdot \mathbf{U} = 0$$

$$\mathbf{U} = (u, 0, w)$$

$$\rho(\mathbf{U} \cdot \nabla)u = -\frac{\partial p}{\partial x} + (\mathbf{j} \times \mathbf{B}) \cdot \mathbf{i} + \mu \frac{\partial^2 u}{\partial z^2}$$

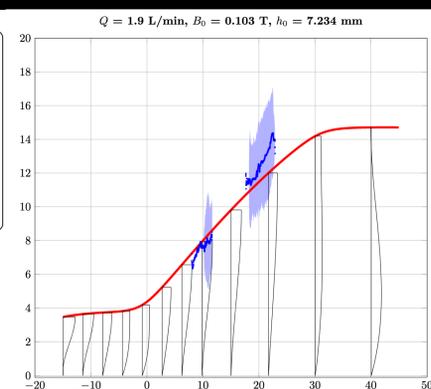


Fig. 4. Analytical review

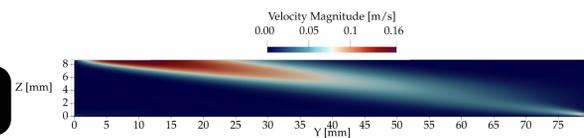


Fig. 7. Cross section velocity field with tungsten substrate ($B_n = 0.1$ T, $B_\phi = 1$ T).

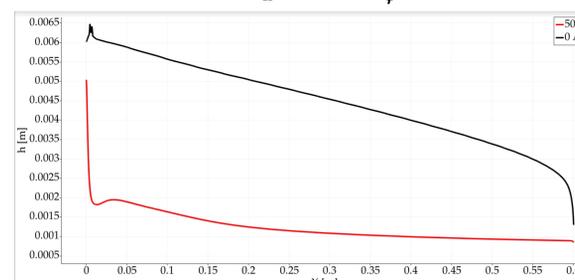


Fig. 8. Height for insulated substrate ($B_n = 0.1$ T, $B_\phi = 1$ T)

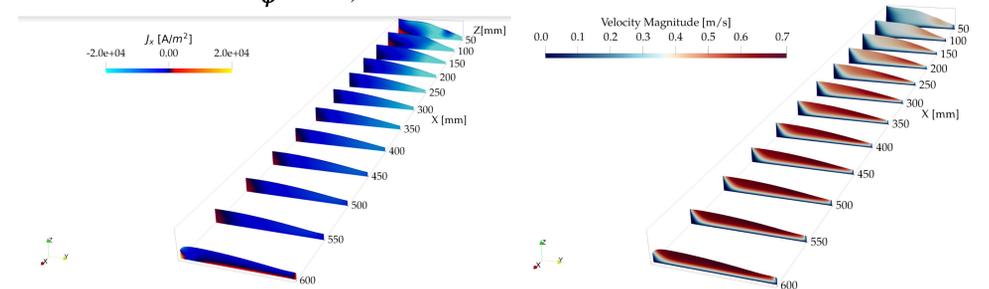


Fig. 9. Flow velocity and axial currents for insulated substrate ($B_n = 0.1$ T, $B_\phi = 1$ T, 50 A)

Conclusions

- Requirements to overcome MHD drag are incompatible with cost-effective reactors.
- Simplified analytical equations to describe MHD flows do not encompass relevant 3D effects. Simulations are required.
- Current injection may accelerate a liquid metal flow but also causes unstable behavior.
- Axial currents in developing linear flows are inevitable and pose issues for reactor operation.

Acknowledgements

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References

[1] E. Kolemen, M. Hvasta, R. Majeski, R. Maingi, A. Brooks, and T. Kozub, "Design of the Flowing Liquid Torus (FLIT)," Nuclear Materials and Energy, vol. 19, pp. 524–530, May 2019, doi: 10.1016/j.nme.2019.01.005.