

Stellarator Phase Space Exploration with DESC

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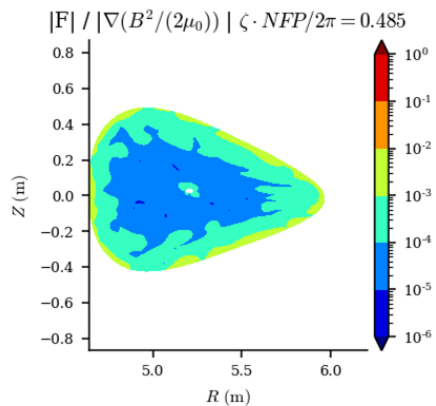
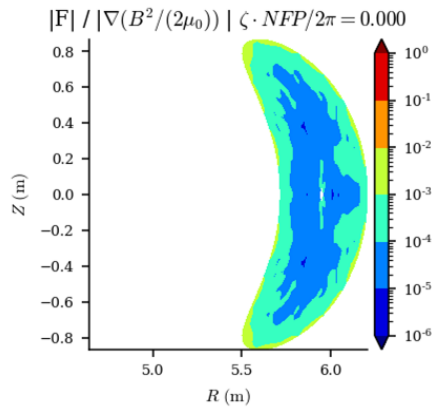
⁴University of Maryland

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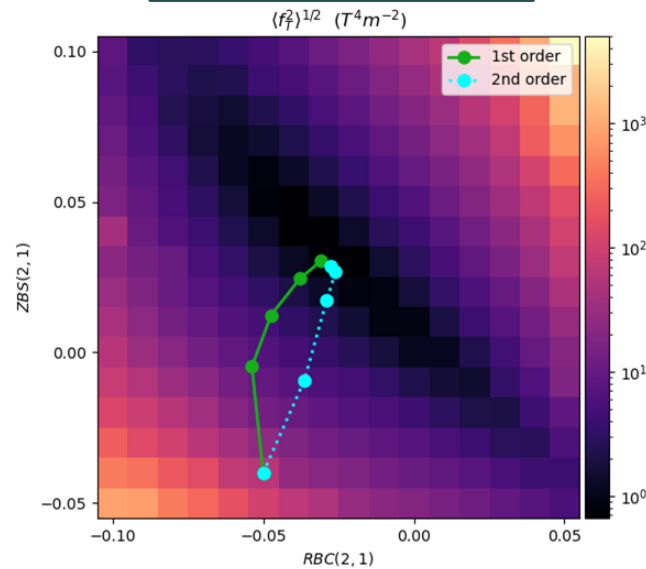


DESC is the ideal tool for stellarator equilibrium solving and optimization

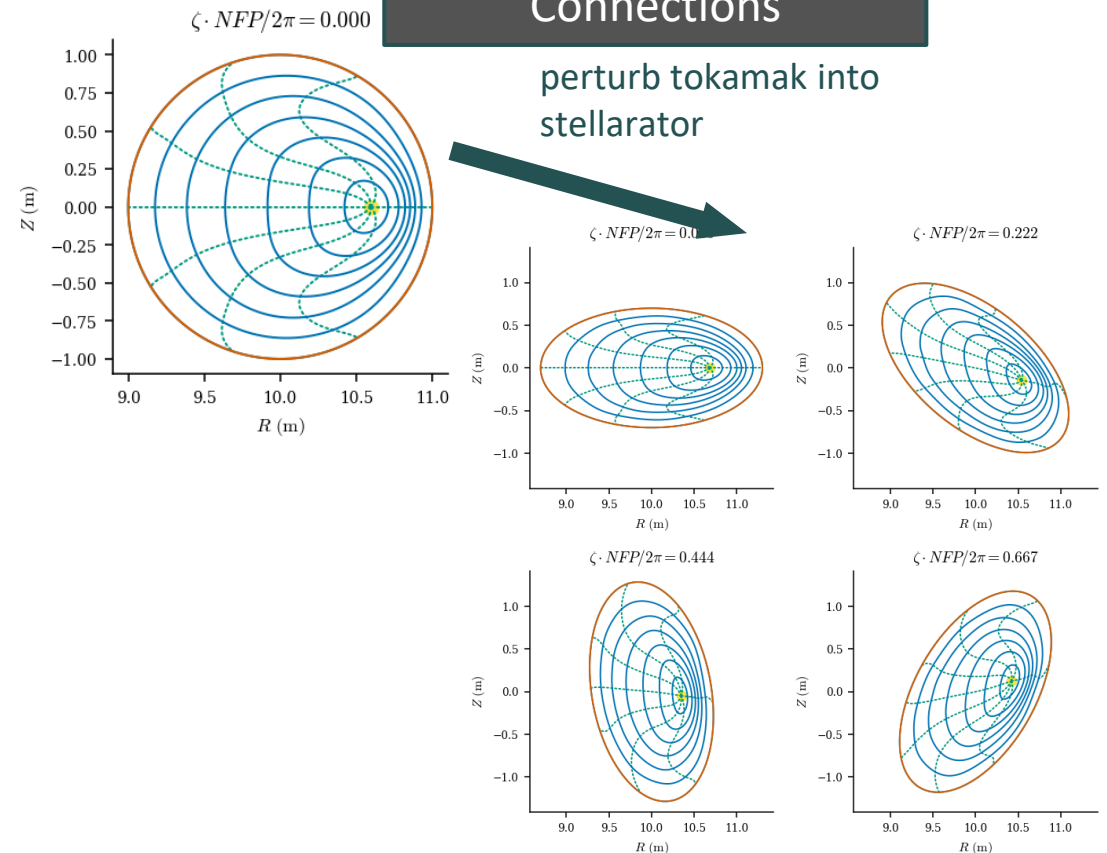
Accurate Equilibria



Fast Optimization



Phase-Space Connections

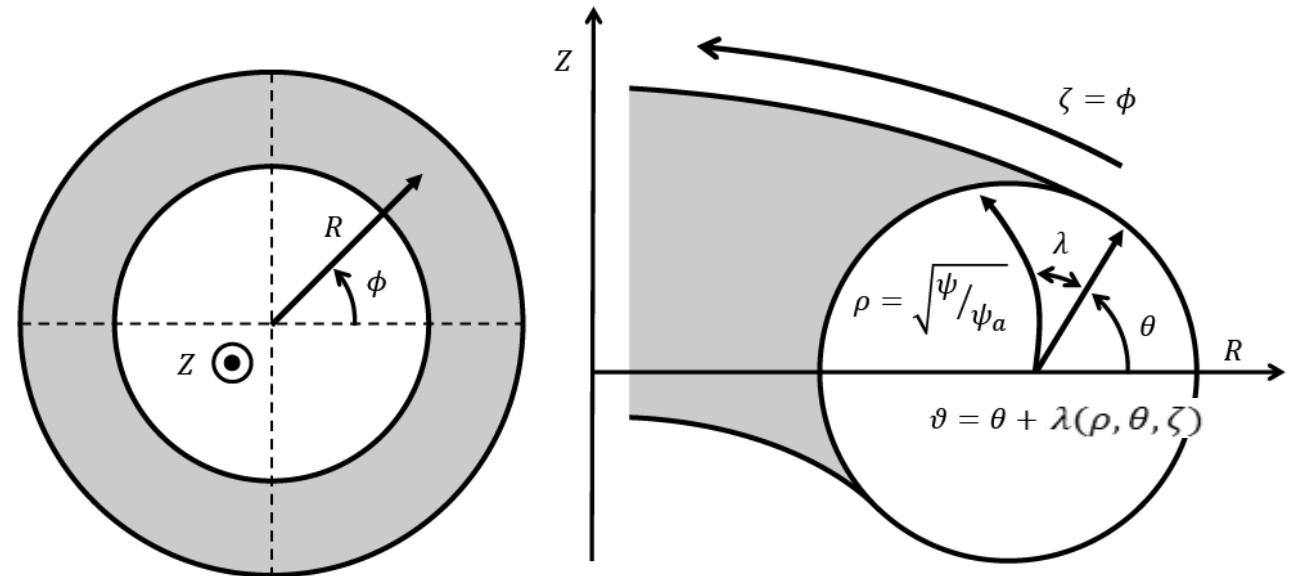


Stellarator Equilibrium and Optimization - DESC



- 3D Ideal MHD Equilibrium Code
- Assumes Nested Flux Surfaces
- Inverse Equilibrium Problem
- Minimizes Force Error Directly
$$\mathbf{F} = \mathbf{J} \times \mathbf{B} - \nabla p = 0$$
- Pseudospectral Code

3D Spectral Representation of $\mathbf{x} = (R, \lambda, Z)$ using Fourier-Zernike Basis



What do we want when we design a stellarator?

Non-axisymmetric Magnetic Fields

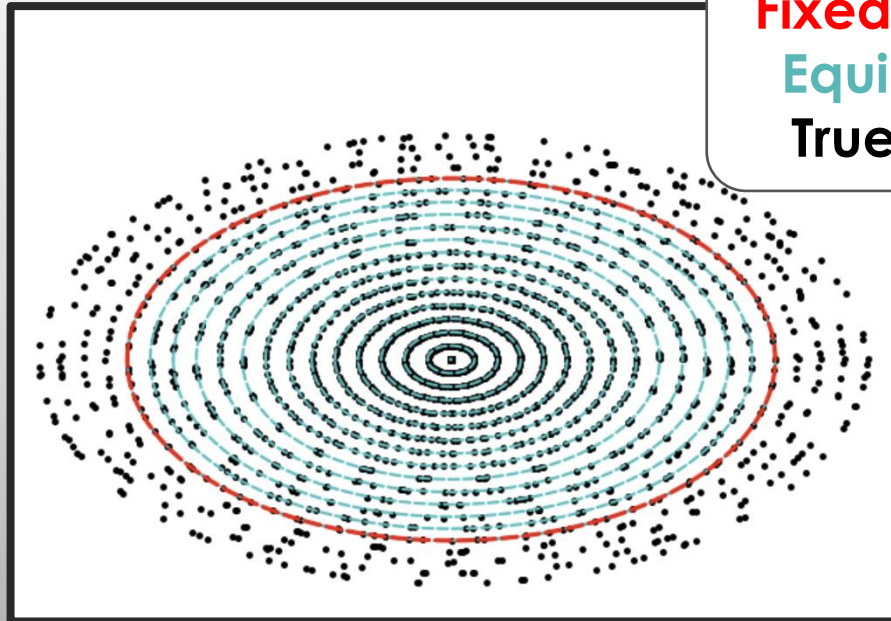
We want nested flux surfaces for confinement

Non-axisymmetric Magnetic Fields

**Nested Flux
Surfaces**

How can we know we will actually get nested flux surfaces?

Non-axisymmetric Magnetic Fields



Fixed-Boundary input
Equilibrium Solution
True Vacuum Field

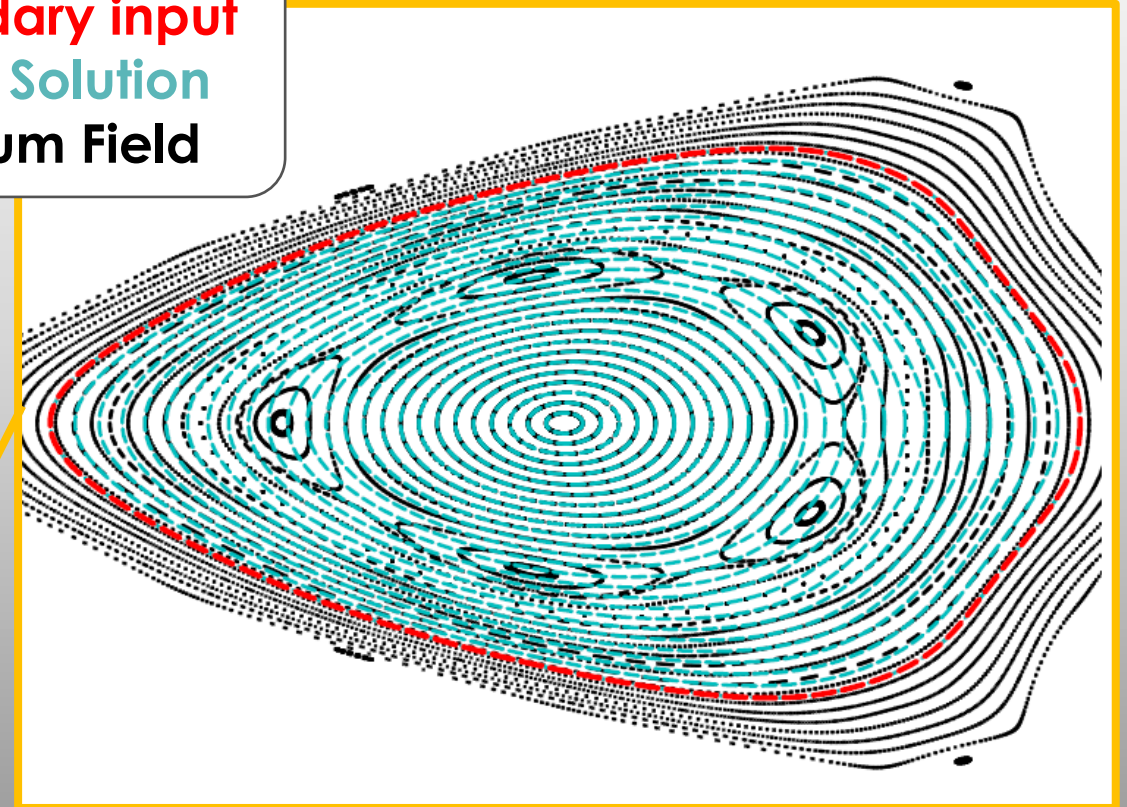
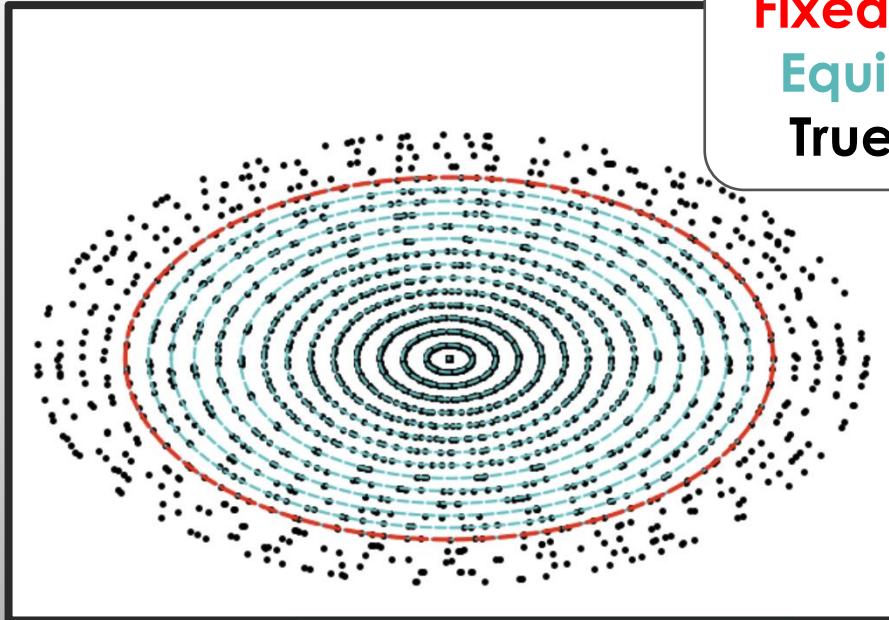
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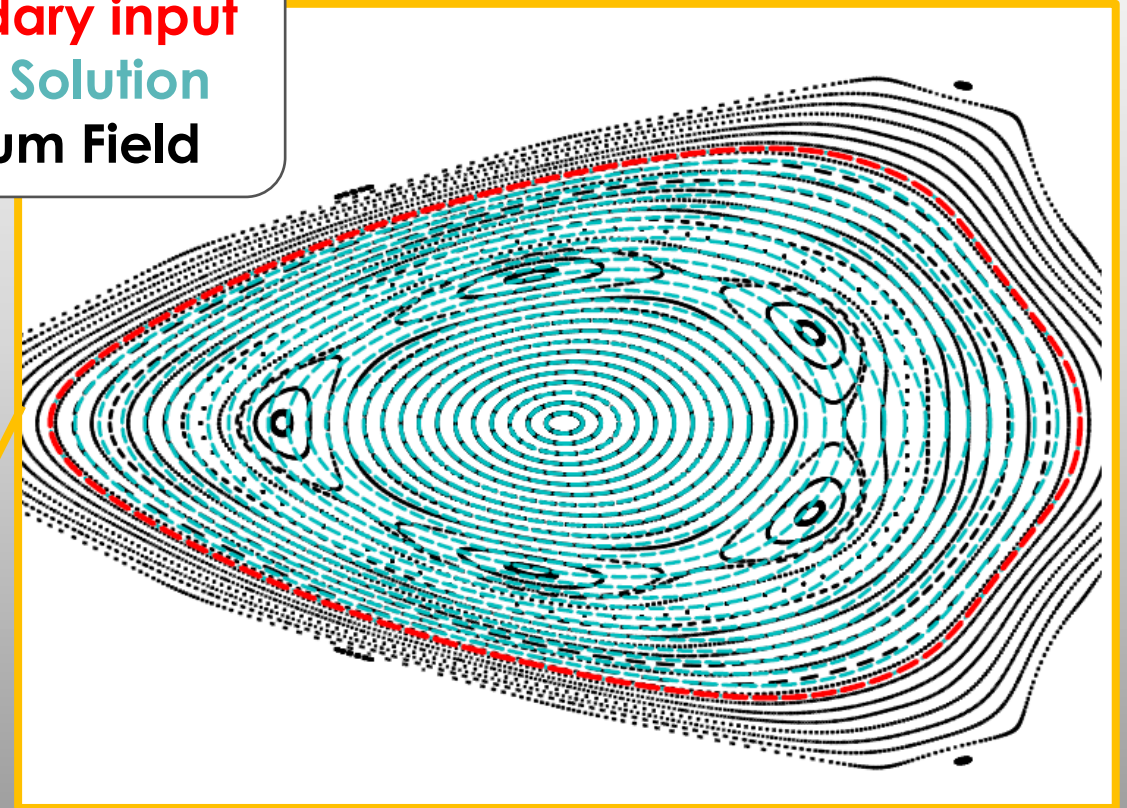
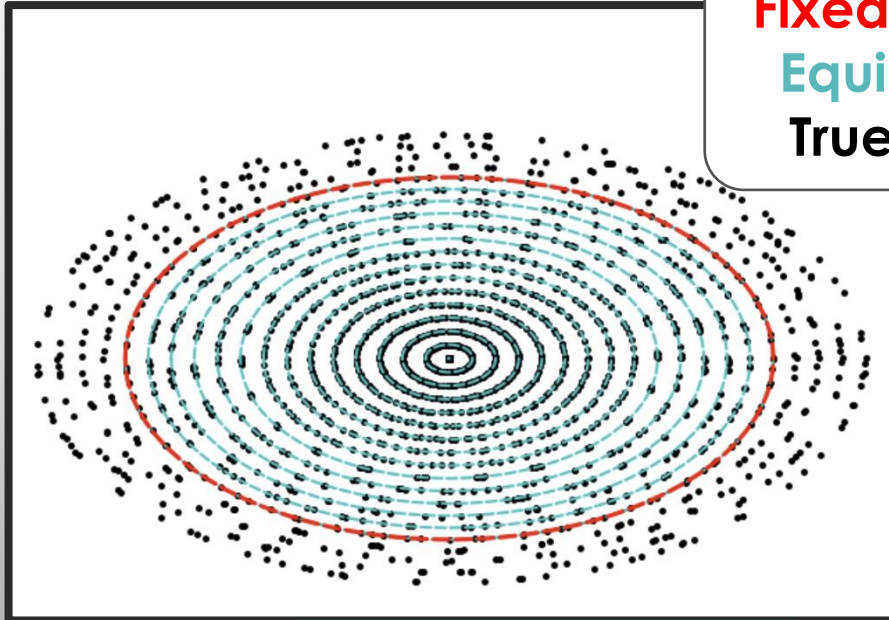
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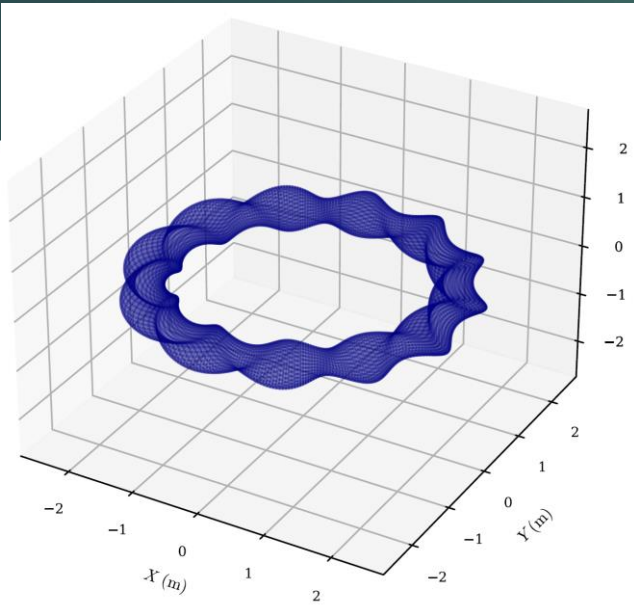


Nested Flux
Surfaces

Define this subspace!

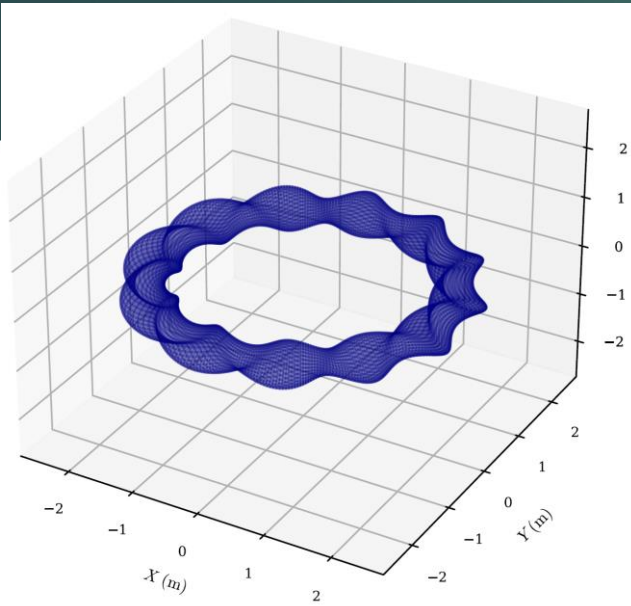
Poincare Boundary Condition

Conventional Last-Closed-Flux-Surface Boundary Condition

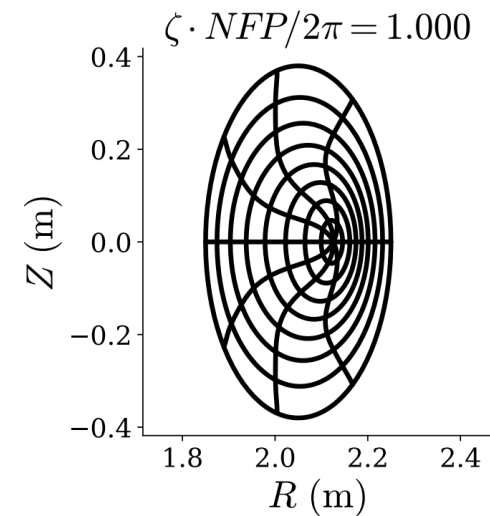
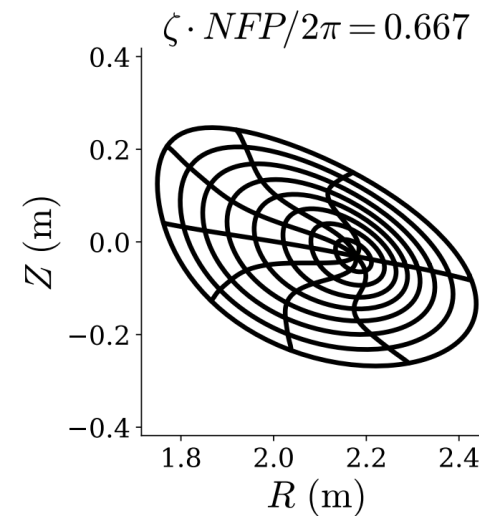
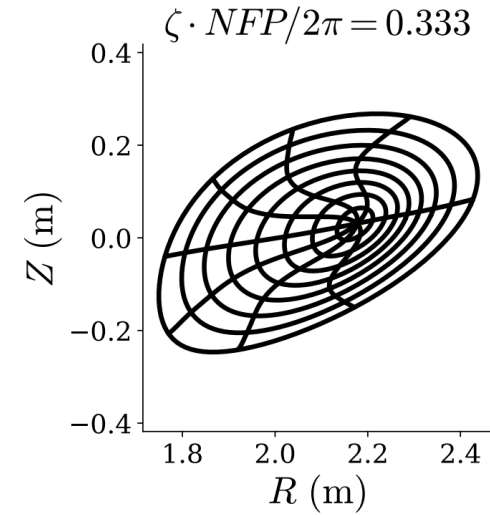
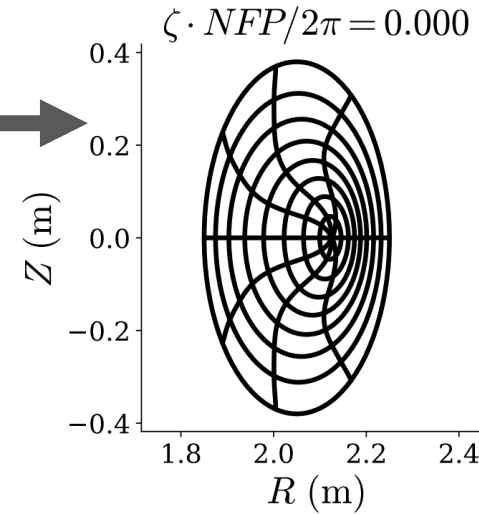


INPUT: R,Z of LCFS at $\rho=1$

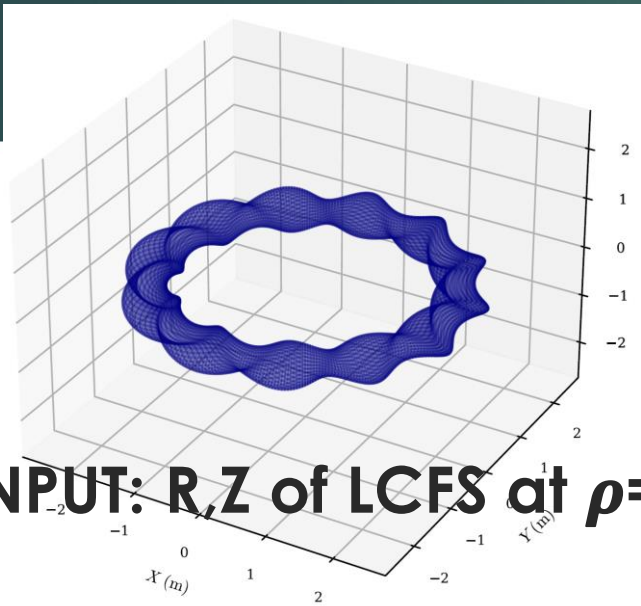
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INPUT: R, Z of LCFS at $\rho=1$

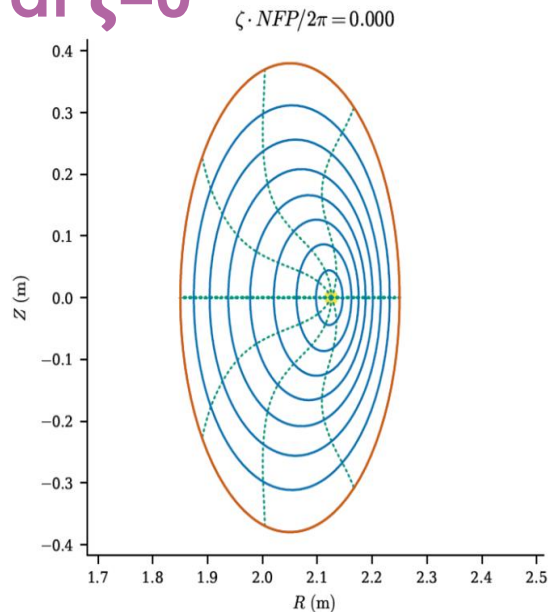


Poincare Section could better parameterize stellarator design space

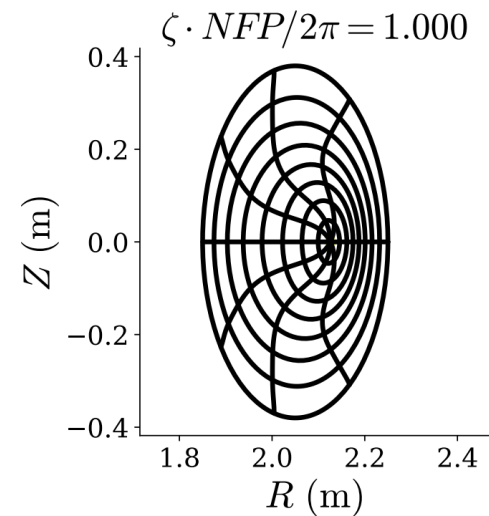
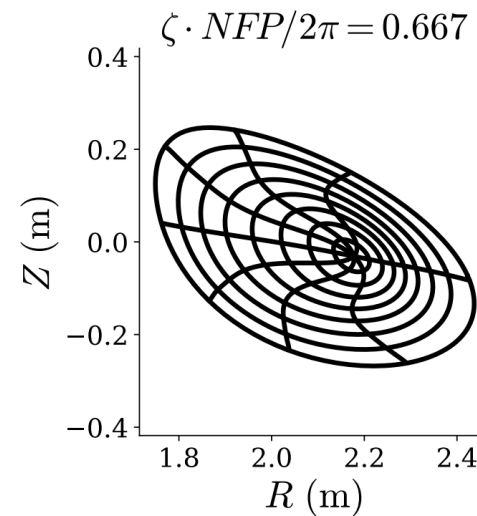
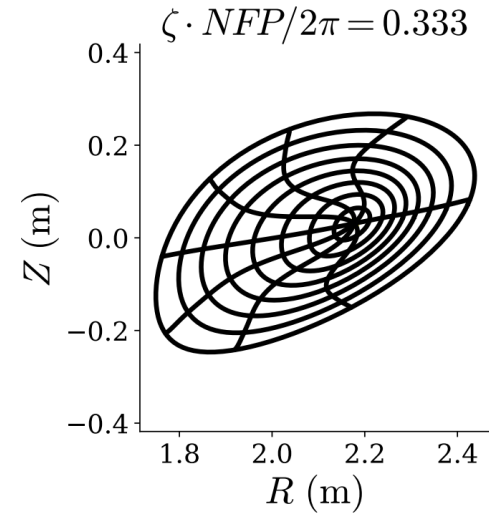
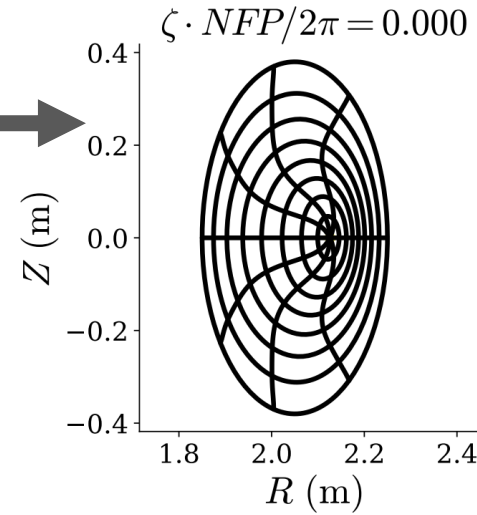


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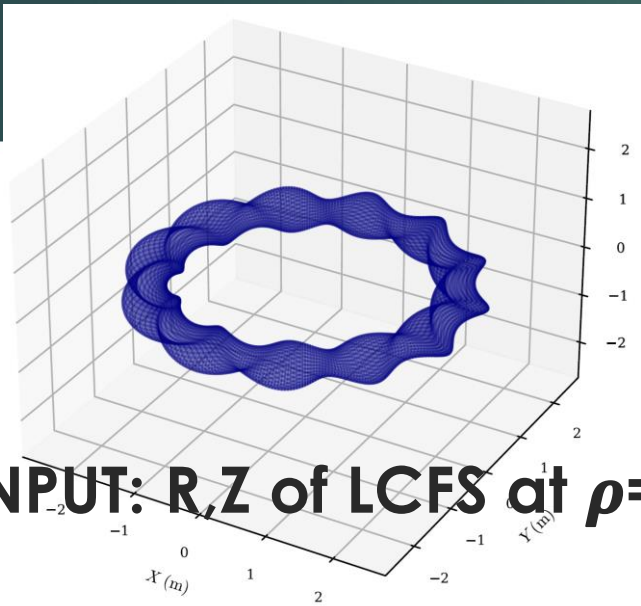
INPUT: R,Z, λ of Poincare XS at $\zeta=0$



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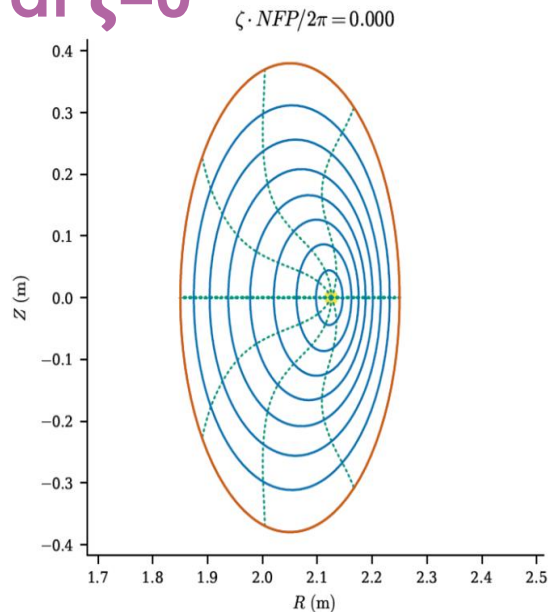


Poincare Section could better parameterize stellarator design space

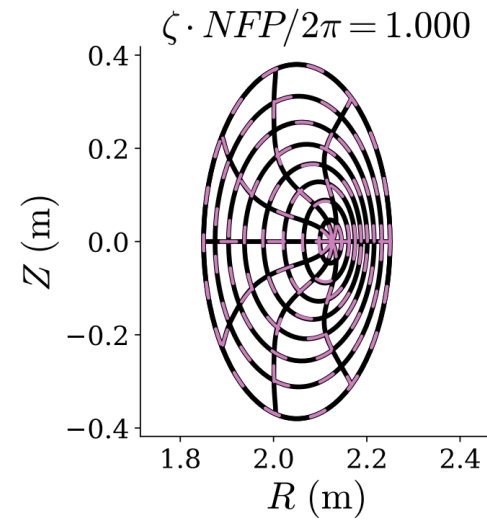
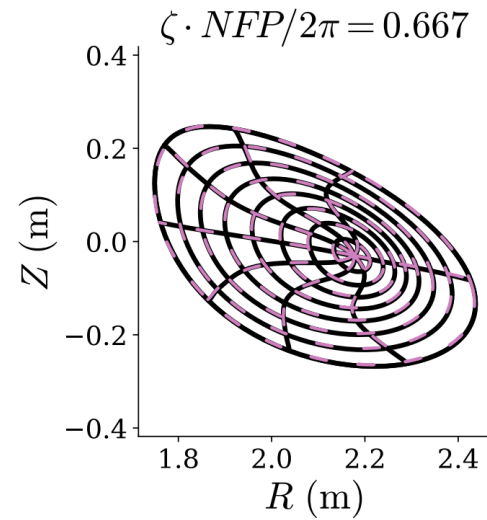
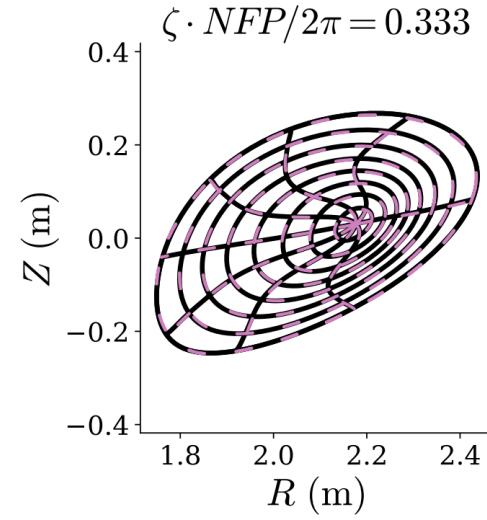
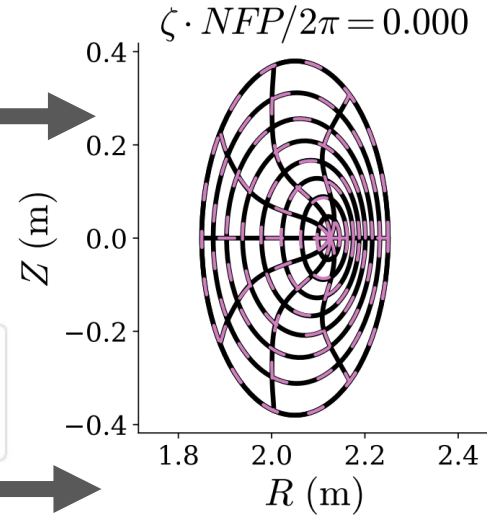


INPUT: R,Z of LCFS at $\rho=1$

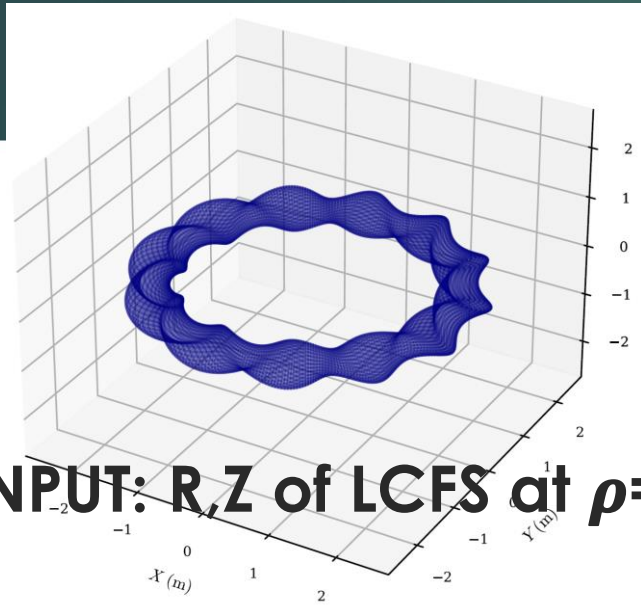
INPUT: R,Z, λ of Poincare XS at $\zeta=0$



— LCFS BC
- - Poincare BC

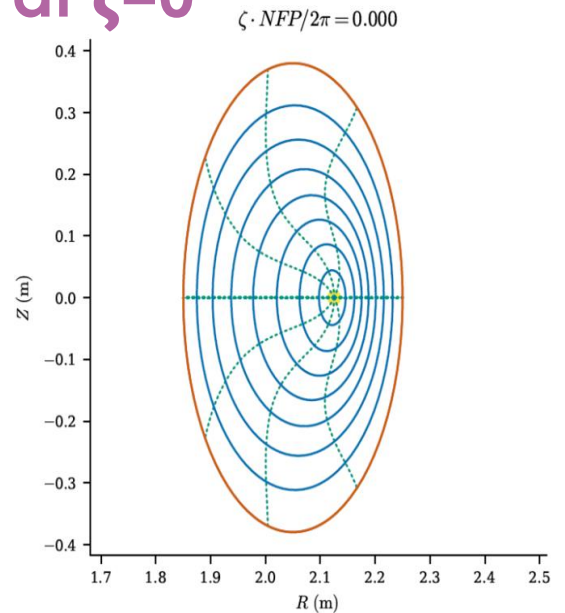


Poincare Section could better parameterize stellarator design space



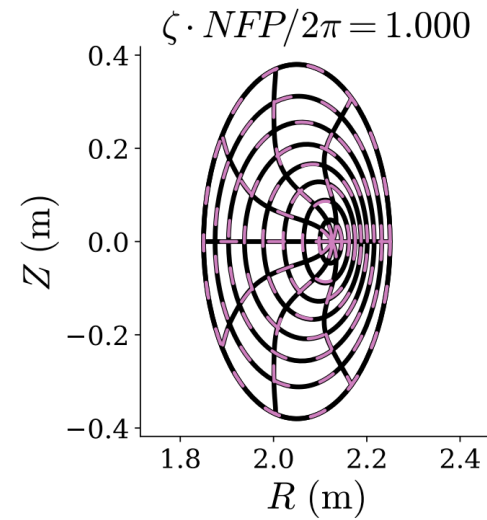
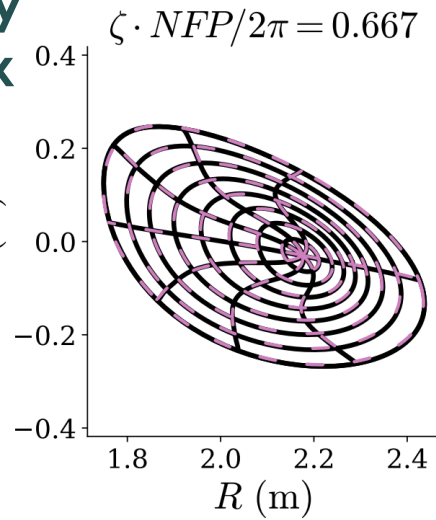
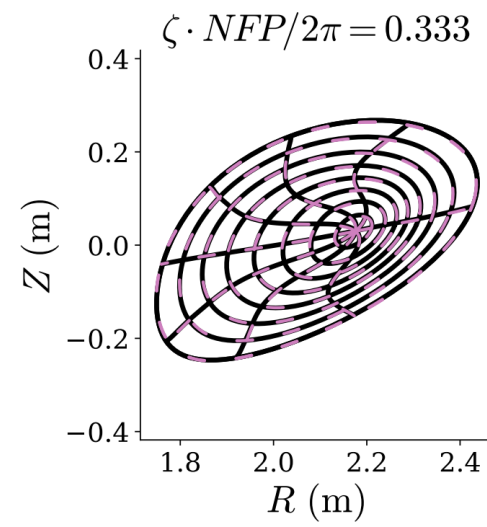
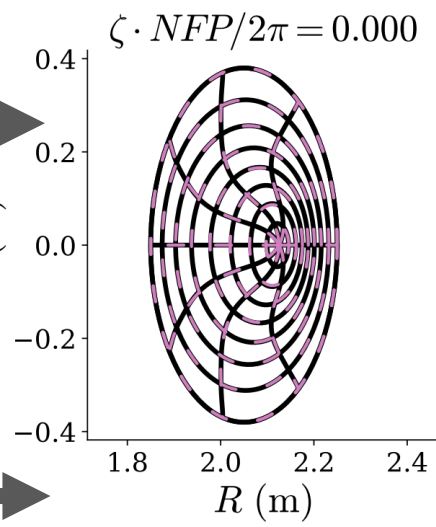
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INPUT: R,Z, λ of Poincare XS at $\zeta=0$



— LCFS BC
- - Poincare BC

- Potentially restrict to only solutions with nested flux surfaces
- Poincare section requires much fewer number input coefficients to describe boundary

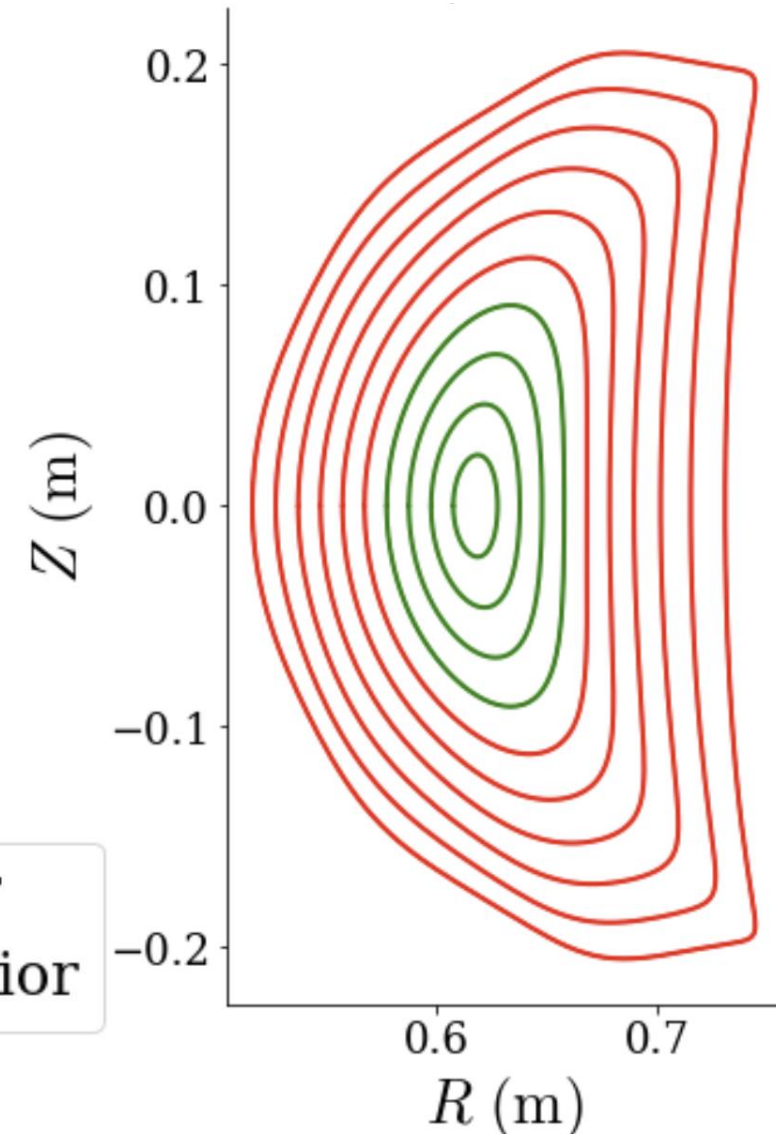


Near-Axis Constrained Equilibria

Given a NAE solution, how do we find a global MHD solution?

NAE equilibrium evaluated at $r = 0.1$

Evaluating and fixing outer surface uses
NAE where it is **least accurate**

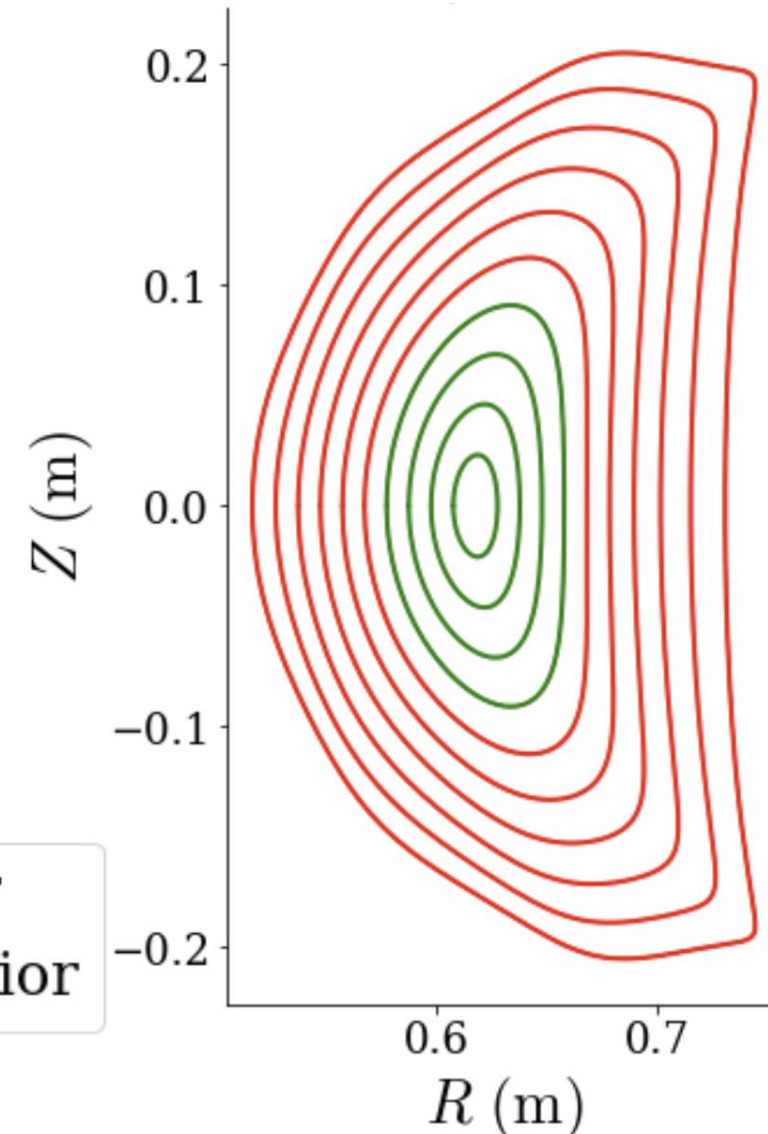


Near-Axis Expansion (NAE) Constraints in DESC (with E. Rodriguez)

- Constrain global equilibrium by NAE behavior as $\rho \rightarrow 0$
 - Use information from NAE where it is **most valid**
 - Avoid singular behavior present when evaluating at **large r**
- Map NAE coefficients to Fourier-Zernike modes of DESC to fix $O(\rho^0)$ (axis) and $O(\rho^1)$ behavior



NAE equilibrium evaluated at $r = 0.1$



$O(\rho^0)$ (axis) Constraint in DESC

Given a NAE axis as Fourier series in cylindrical toroidal angle ϕ :

$$R = R_0 + \sum_{n=1}^N (R_n^C \cos m\phi + R_n^S \sin m\phi)$$

$$Z = \sum_{n=1}^N (Z_n^C \cos m\phi + Z_n^S \sin m\phi)$$

There exists a simple, linear mapping to the DESC Fourier-Zernike basis:

**NAE Axis
Coefficients**

$$R_n^{C/S} = \sum_{k=0}^{\infty} (-1)^k R_{2k,0,\pm|n|}$$

$$Z_n^{C/S} = \sum_{k=0}^{\infty} (-1)^k Z_{2k,0,\pm|n|}$$

**DESC
Fourier-Zernike
Coefficients**

$O(\rho^1)$ NAE Constraint in DESC

- Given $O(\rho)$ R,Z position flux surface from the NAE:

$$\mathbf{r} \approx \mathbf{r}_0(\phi) + \rho R_1 \hat{\mathbf{R}} + \rho Z_1 \hat{\mathbf{Z}}$$

where

$$R_1 = \mathcal{R}_{1,1}(\phi) \cos \theta + \mathcal{R}_{1,-1}(\phi) \sin \theta$$

$$Z_1 = \mathcal{Z}_{1,1}(\phi) \cos \theta + \mathcal{Z}_{1,-1}(\phi) \sin \theta$$

There again exists a simple, linear mapping to the DESC Fourier-Zernike basis:

**NAE
Coefficients**

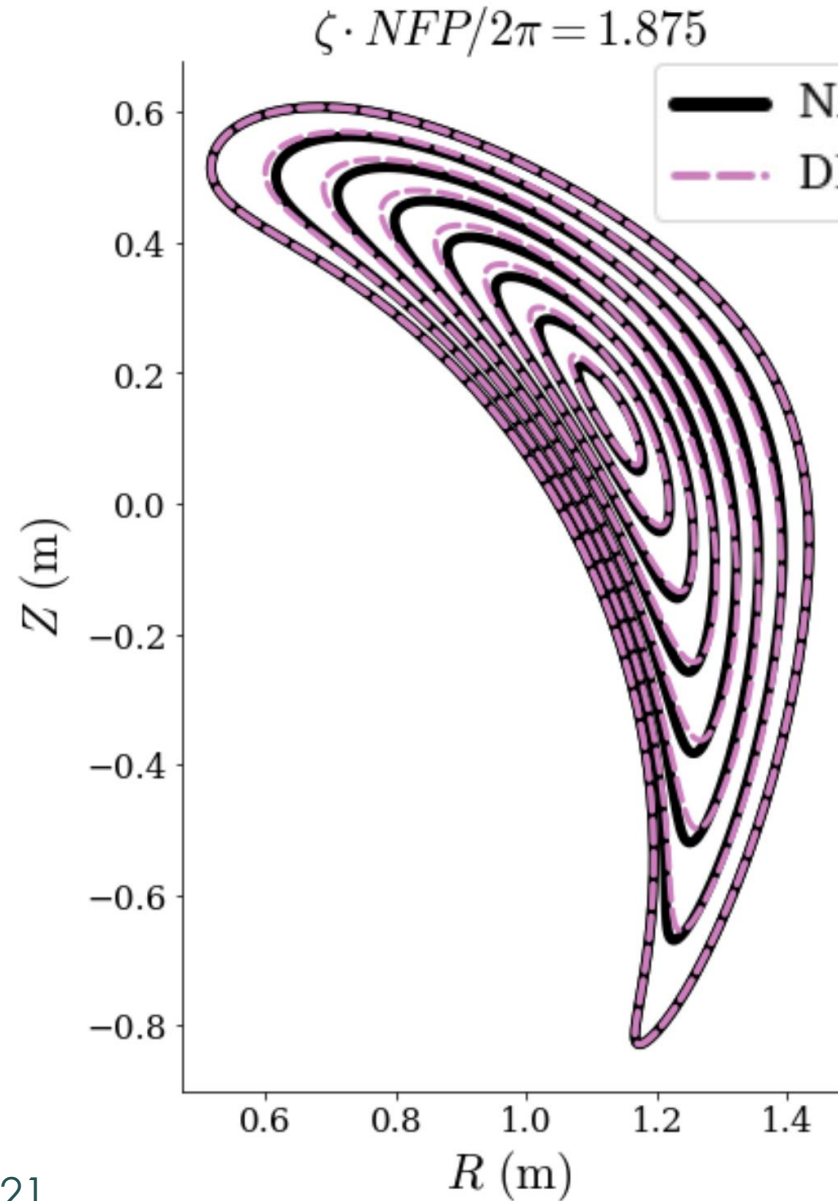
$$\mathcal{R}_{1,1,n} = - \sum_{k=1}^M (-1)^k k R_{2k-1,1,n},$$
$$\mathcal{R}_{1,-1,n} = - \sum_{k=1}^M (-1)^k k R_{2k-1,-1,n},$$

**DESC
Fourier-Zernike
Coefficients**



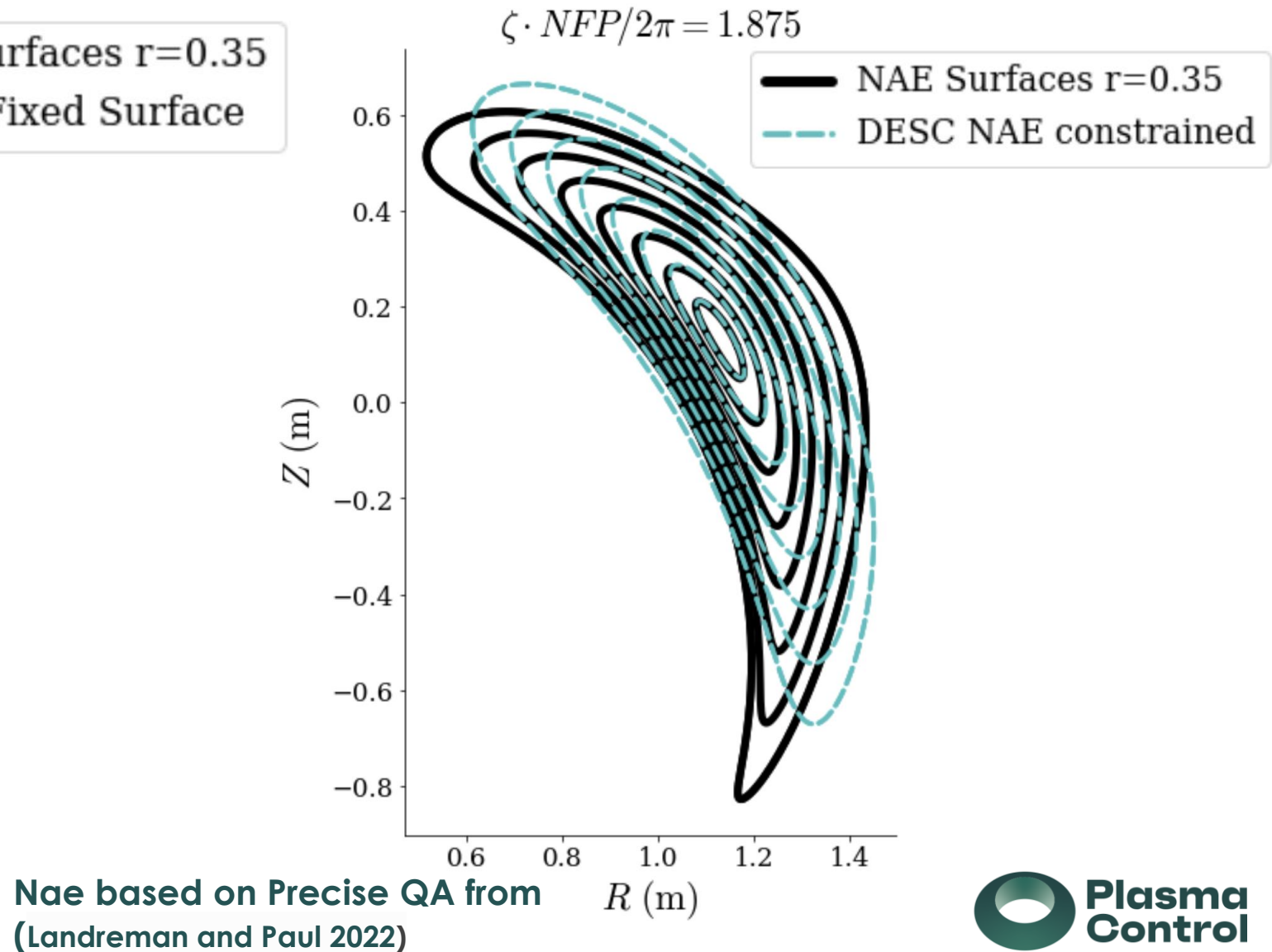
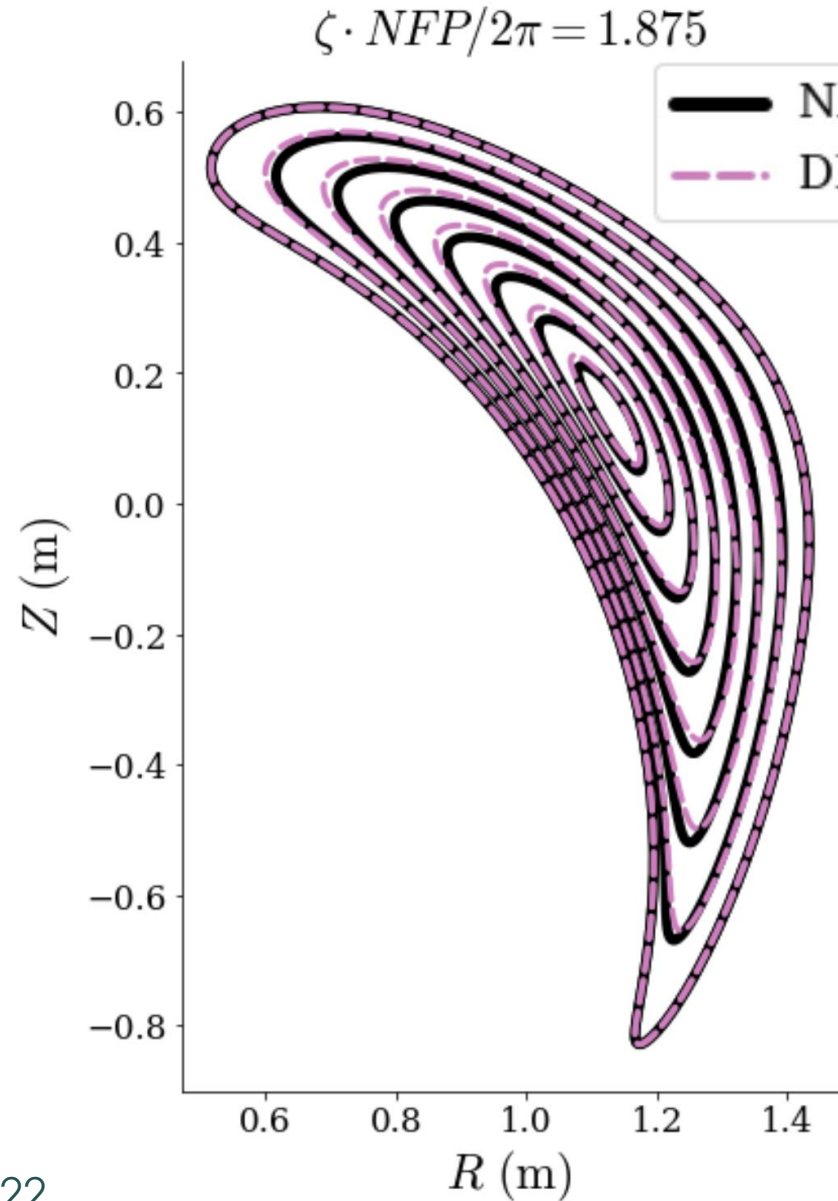
(Identical expressions for Z)

Fixed-Boundary Solve from NAE surface



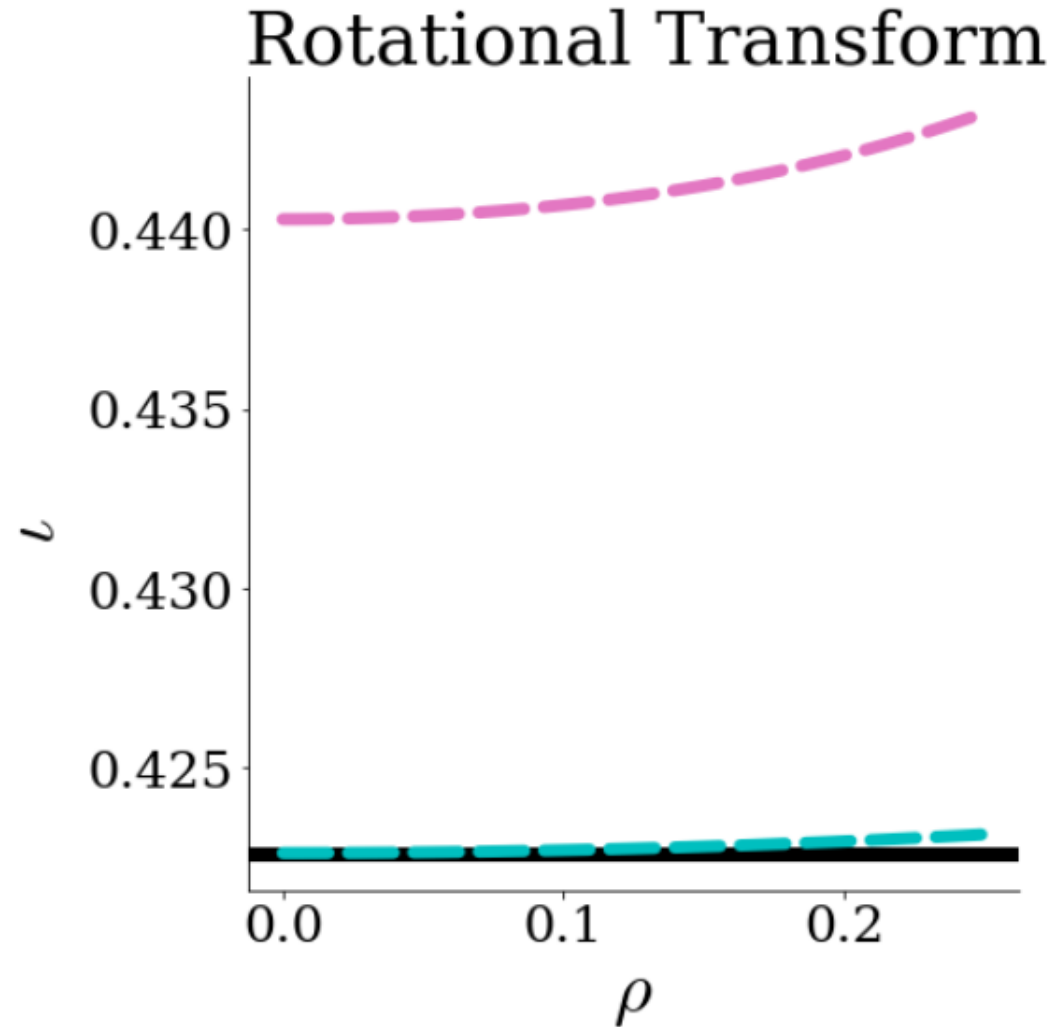
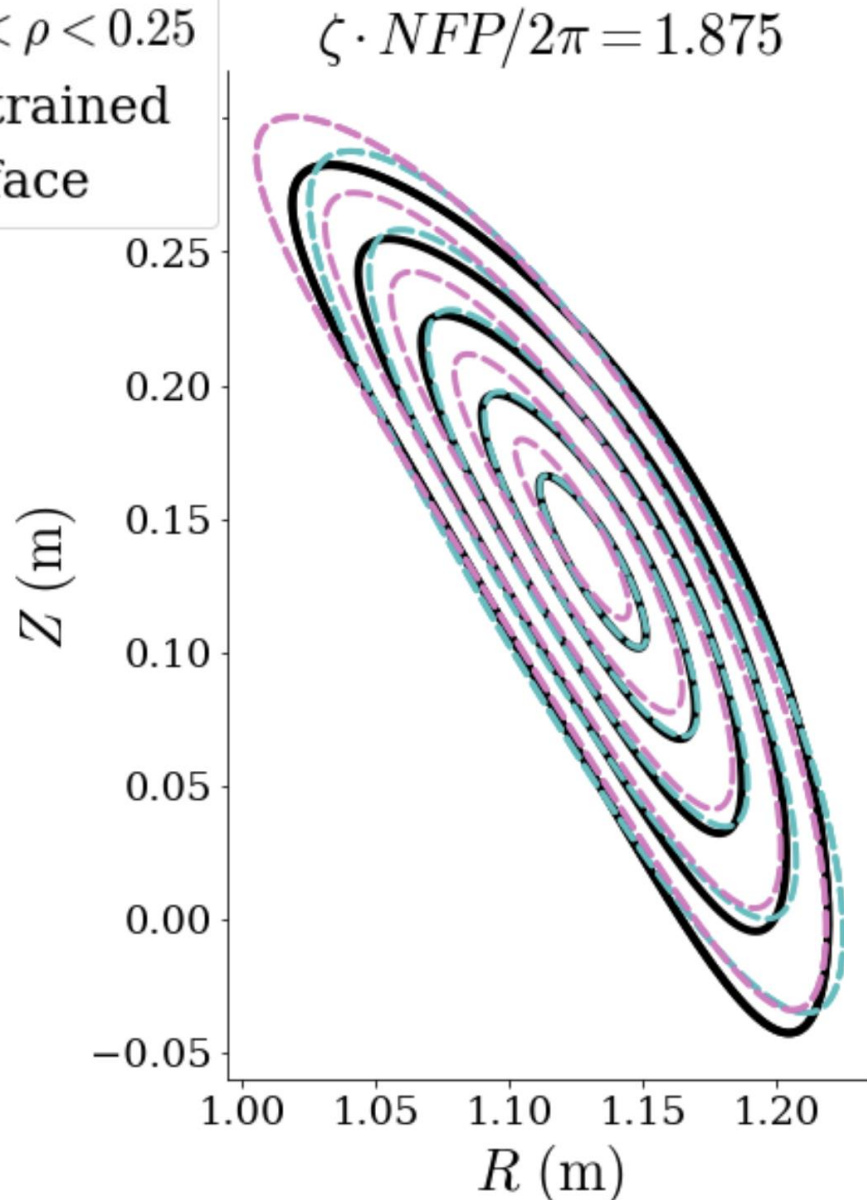
Nae based on Precise QA from
(Landreman and Paul 2022)

NAE Constraint in DESC - Solved Equilibrium Agrees with NAE surfaces NEAR-AXIS, unlike Surface Solve



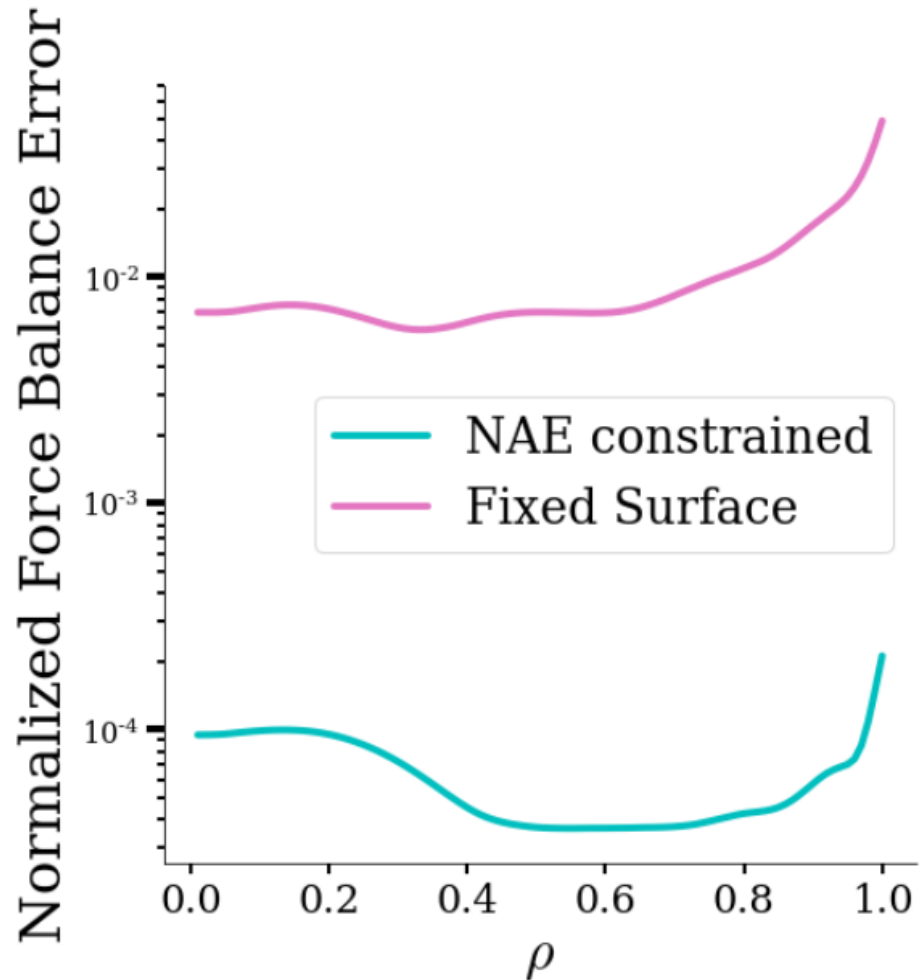
NAE Constraint in DESC - Solved Equilibrium Agrees with NAE surfaces NEAR-AXIS, unlike Surface Solve

- NAE Surfaces $0 < \rho < 0.25$
- - - DESC NAE constrained
- · - DESC Fixed Surface

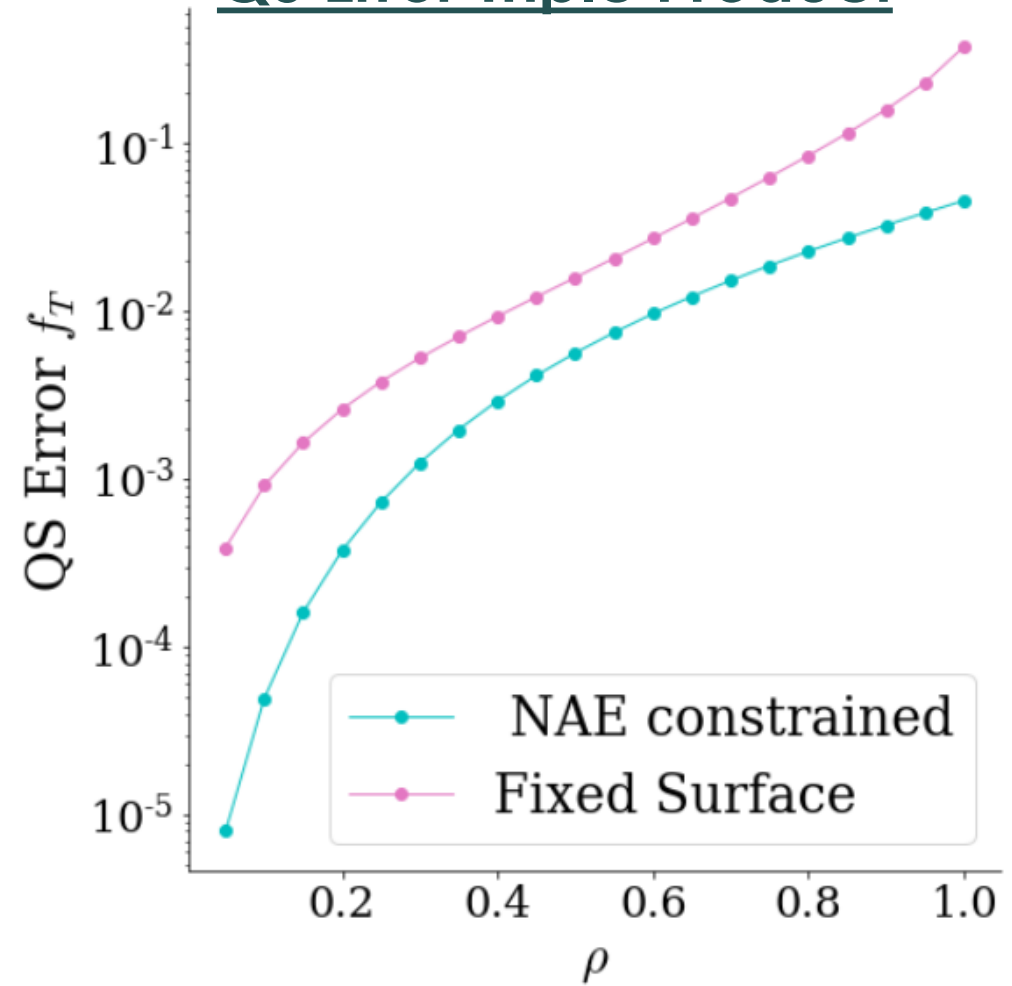


NAE Constraint in DESC - Lower Force Error and Retains QS near-axis

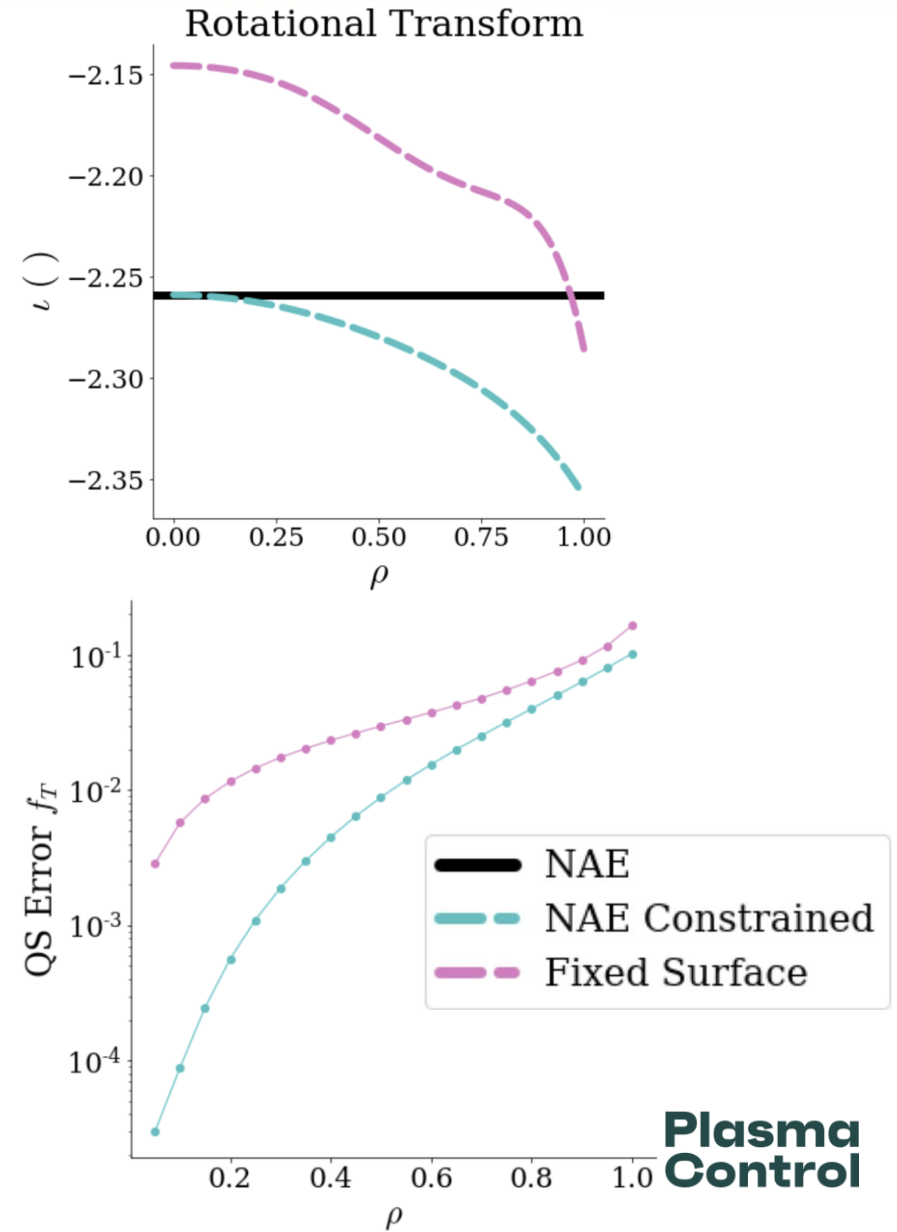
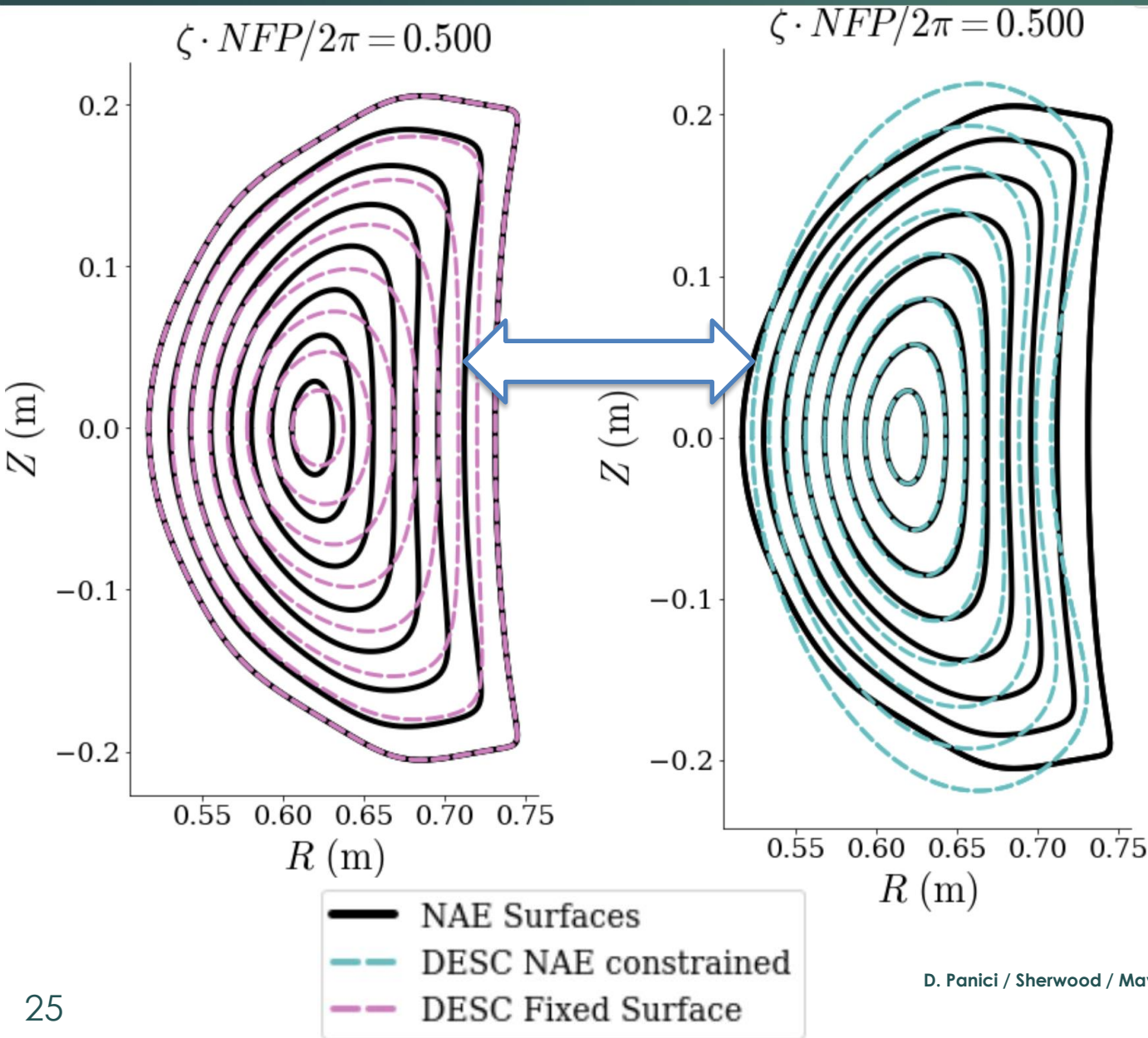
Force Error



QS Error Triple Product



$O(\rho^1)$ Constraint in DESC - Example Solve where Fixed Surface Struggles (Example From E. Rodriguez)



D. Panici / Sherwood / May 2023

We want more than just nested flux surfaces

Nested Flux Surfaces

We want more than just nested flux surfaces

Nested Flux Surfaces

Omnigenous Fields

We want more than just nested flux surfaces

Nested Flux Surfaces

Omnigenous Fields
Define this subspace!

Quasisymmetric Fields

Omnigenous Phase Space Definition

Omnigenous magnetic fields

Particles in omnigenous magnetic fields have no net radial drifts

Conditions for Omnigenity:

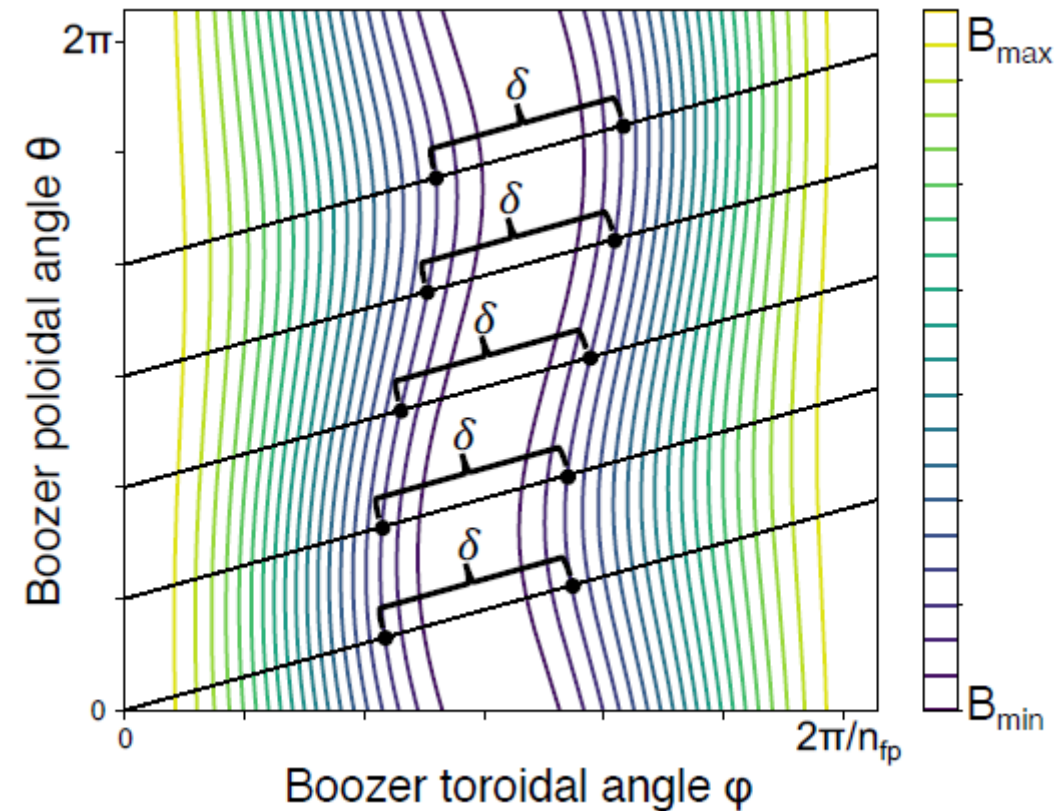
- B_{max} is a straight contour in Boozer coordinates
- Constant "bounce distance" δ between consecutive points of equal B on each field line α

$$\delta = \sqrt{\Delta\theta_B^2 + \Delta\zeta_B^2} \propto \Delta\zeta_B \quad \frac{\partial\delta}{\partial\alpha} = 0$$

Model Assumptions:

- Single magnetic well per field period
- No stellarator symmetry assumption

Quasi-Isodynamic (QI) magnetic fields = omnigenous magnetic fields with constant $|B|$ contours that close poloidally



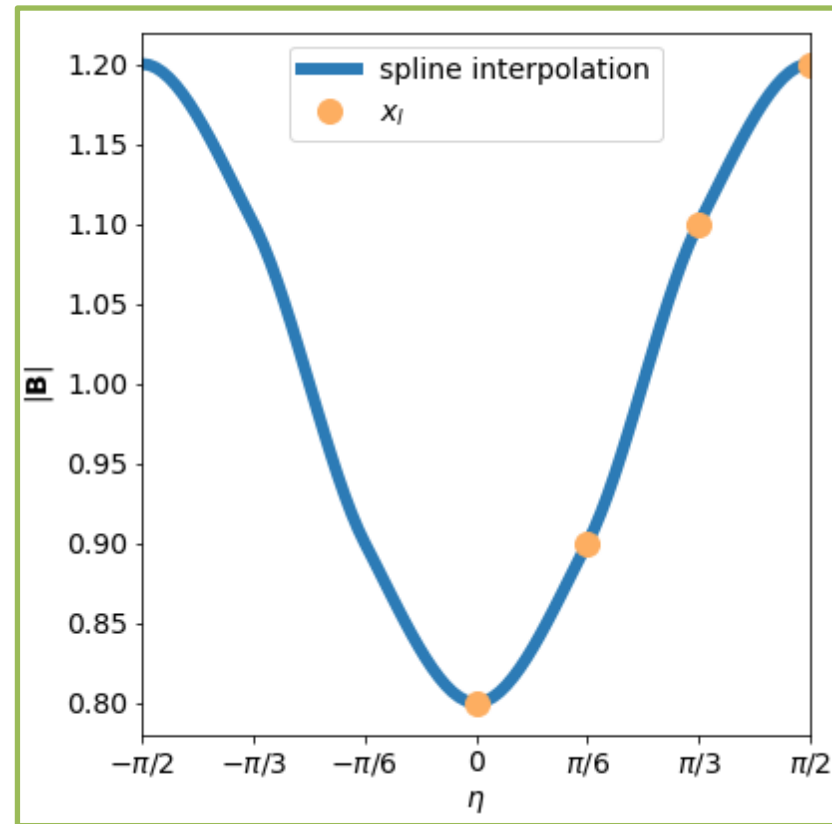
Omnigenity Optimization Through Omnigenous Phase Space Definition

- **Idea: Create a model that can describe any omnigenous field of interest**
- **Then, in optimization we can penalize the difference between the target omnigenous field and the equilibrium's field**

$$f_{OM} = B_{eq}(\alpha, \eta) - B_{OM}(\alpha, \eta)$$

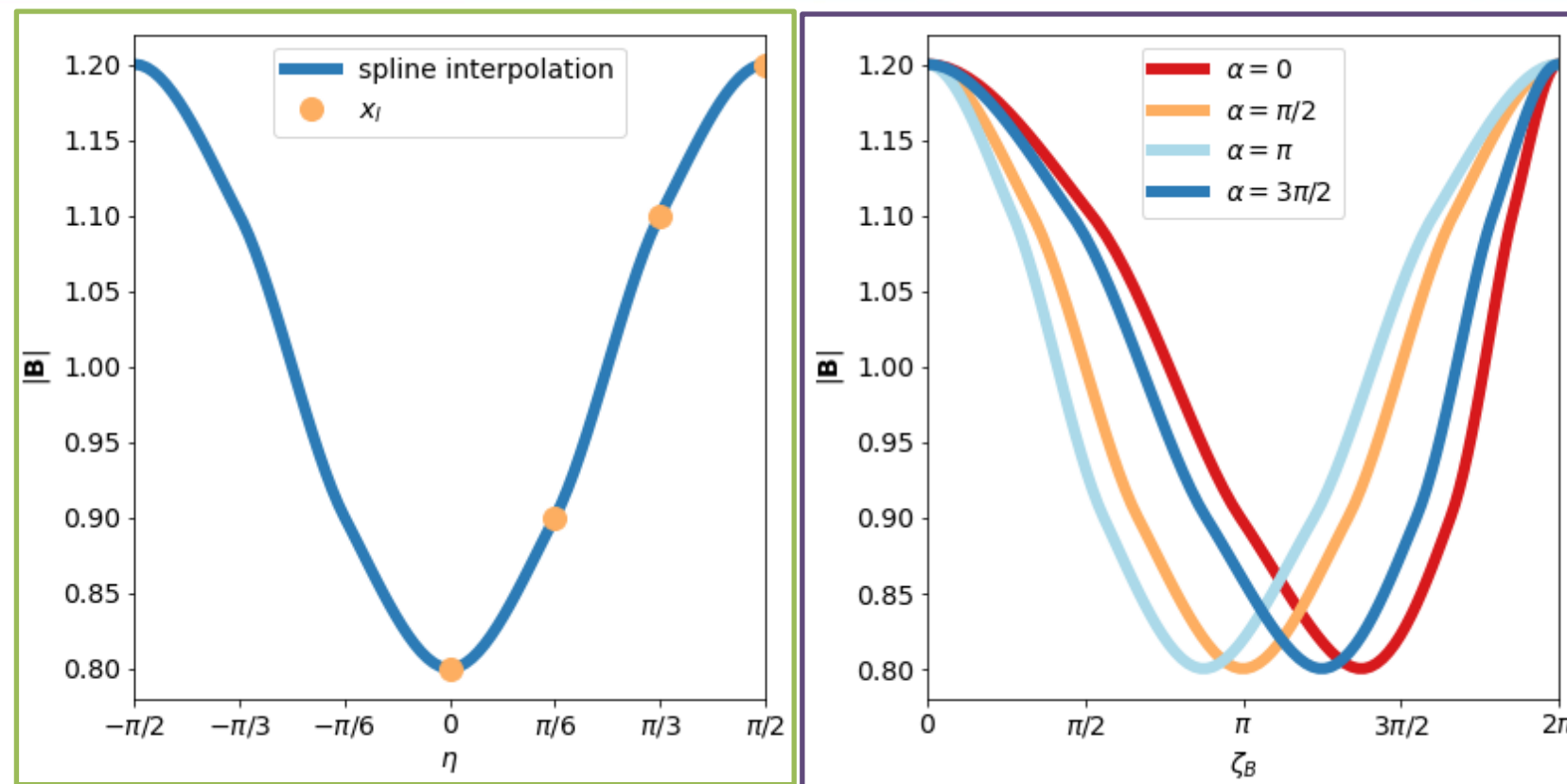
- **Because we parametrize the omnigenous field, we are free to:**
 - **Keep parametrization the same (target a specific omnigenous field)**
 - **Allow the parametrization to be part of the optimization (optimize for SOME omnigenous field)**

Example: Full QI Phase Space Definition in DESC



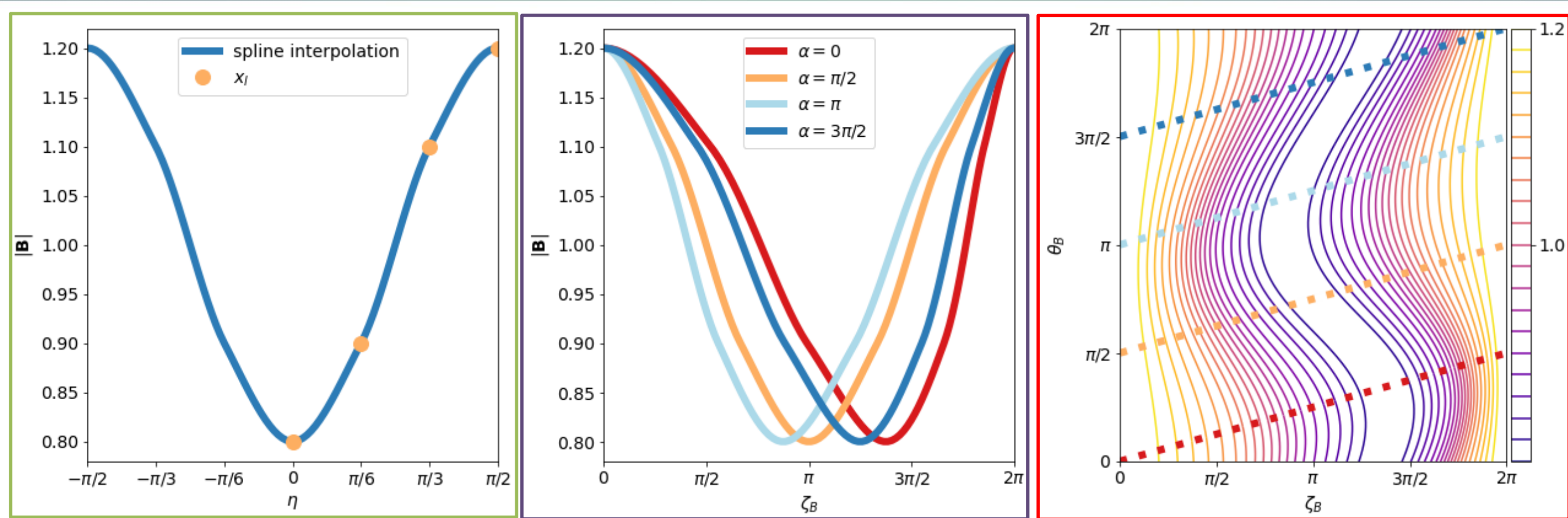
- Specify the magnetic well “shape” in computational coordinate η

Example: Full QI Phase Space Definition in DESC



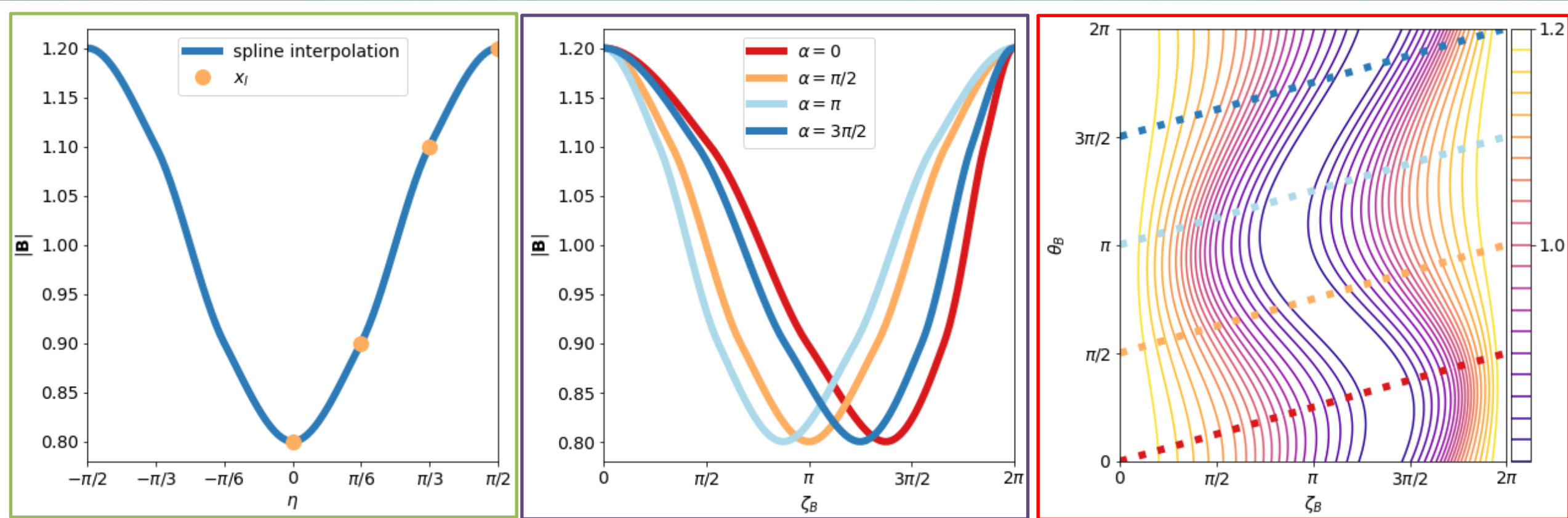
- Specify the magnetic well “shape” in computational coordinate η
- Specify how the well “shifts” on different field lines with a Fourier series x_{mn} in (η, α)

Example: Full QI Phase Space Definition in DESC



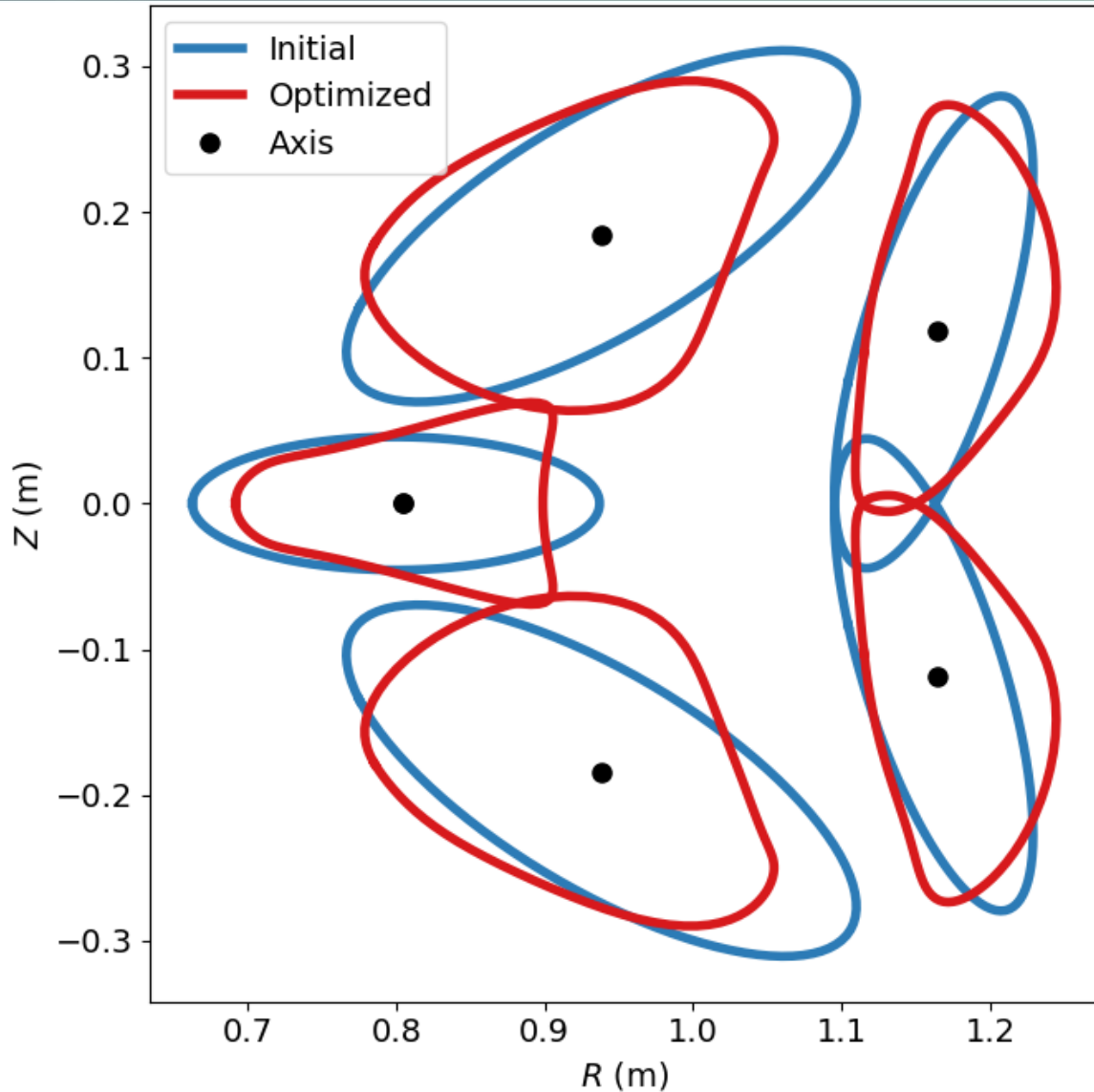
- Specify the magnetic well "shape" in computational coordinate η
- Specify how the well "shifts" on different field lines with a Fourier series x_{mn} in (η, α)
- Generate arbitrary QI magnetic field targets without prior initialization

Example: Full QI Phase Space Definition in DESC



- Specify the magnetic well "shape" in computational coordinate η
- Specify how the well "shifts" on different field lines with a Fourier series x_{mn} in (η, α)
- **Generate arbitrary QI magnetic field targets without prior initialization**
- **Model enables scans of the QI optimization landscape**

Example 1: unconstrained QI target



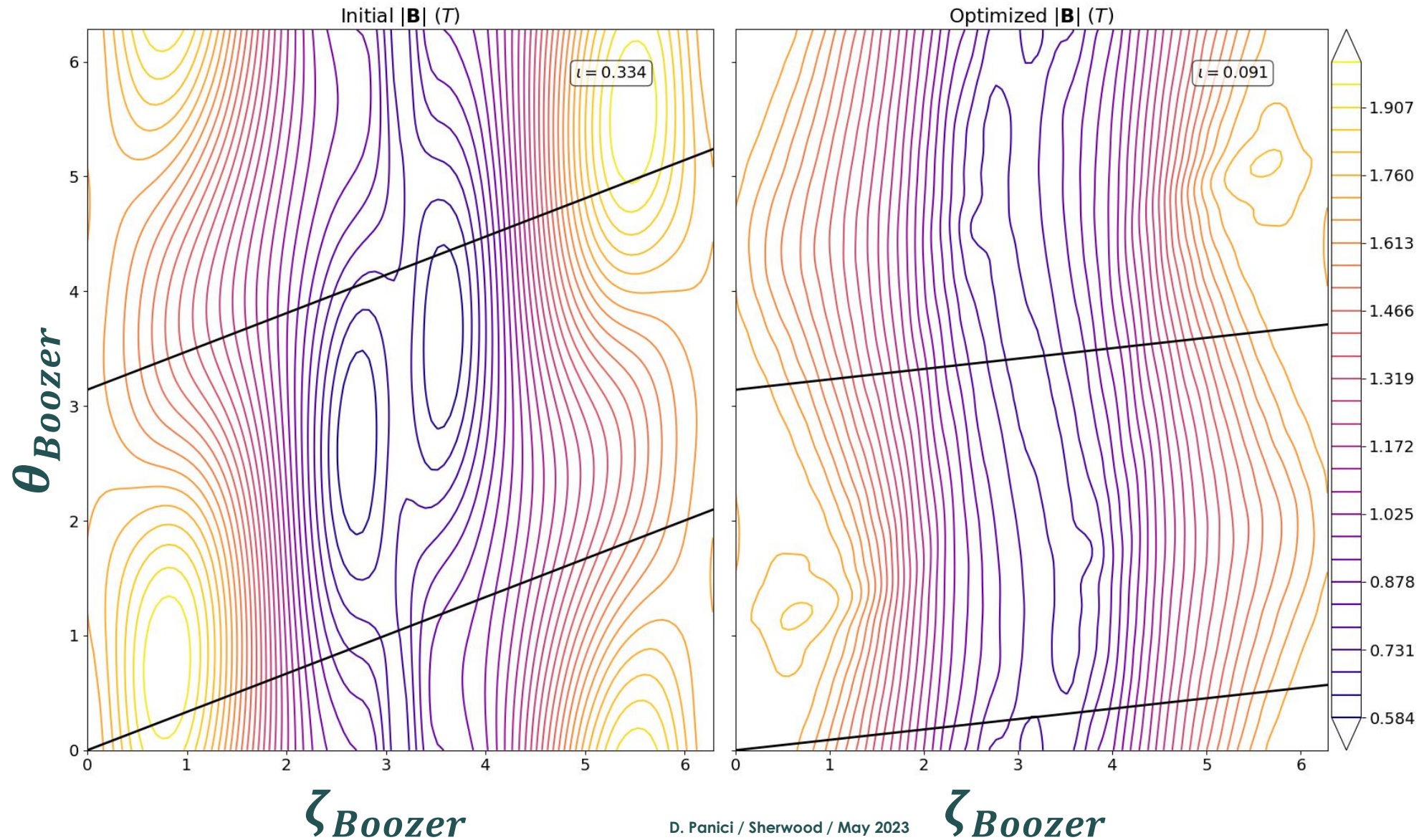
Initial equilibrium:

- Analytic QI model
- Fixing axis of equilibrium

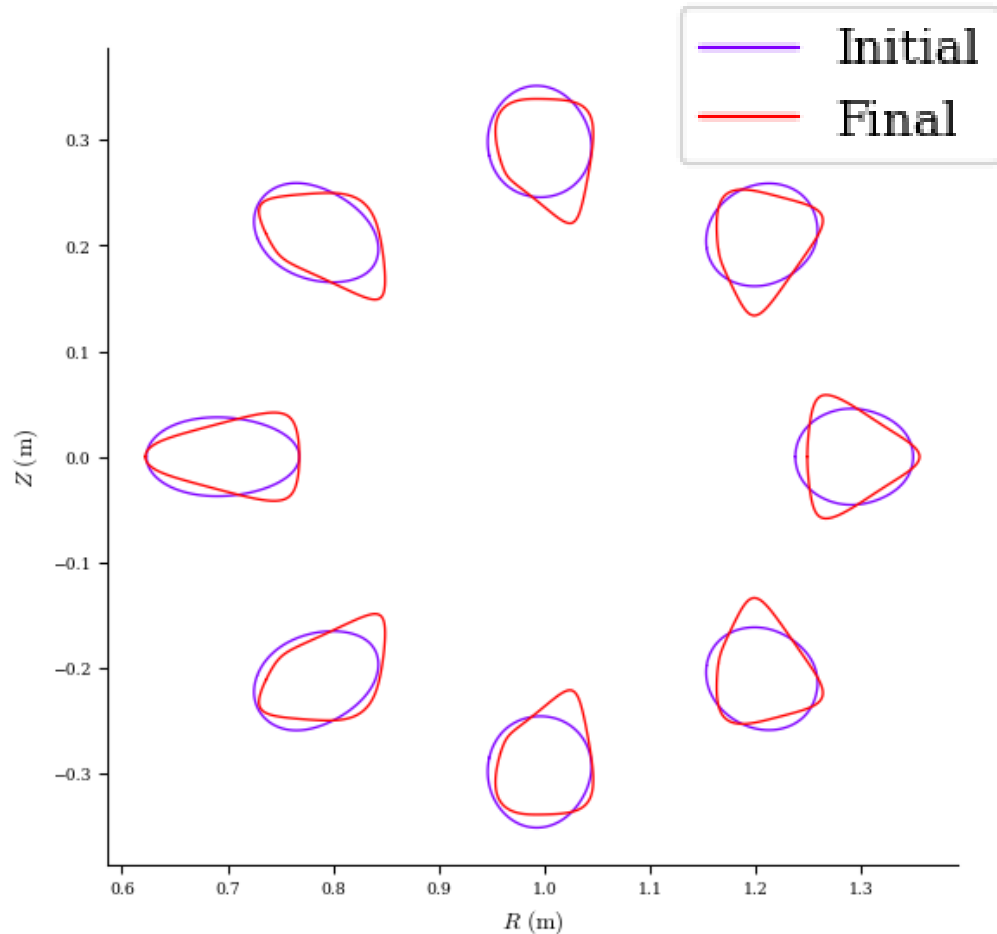
Optimization targets:

- Unconstrained QI on multiple surfaces
(target field allowed to vary)
- Vacuum force balance

Example 1: unconstrained QI target



Example 2: Toroidally closed omnigenity



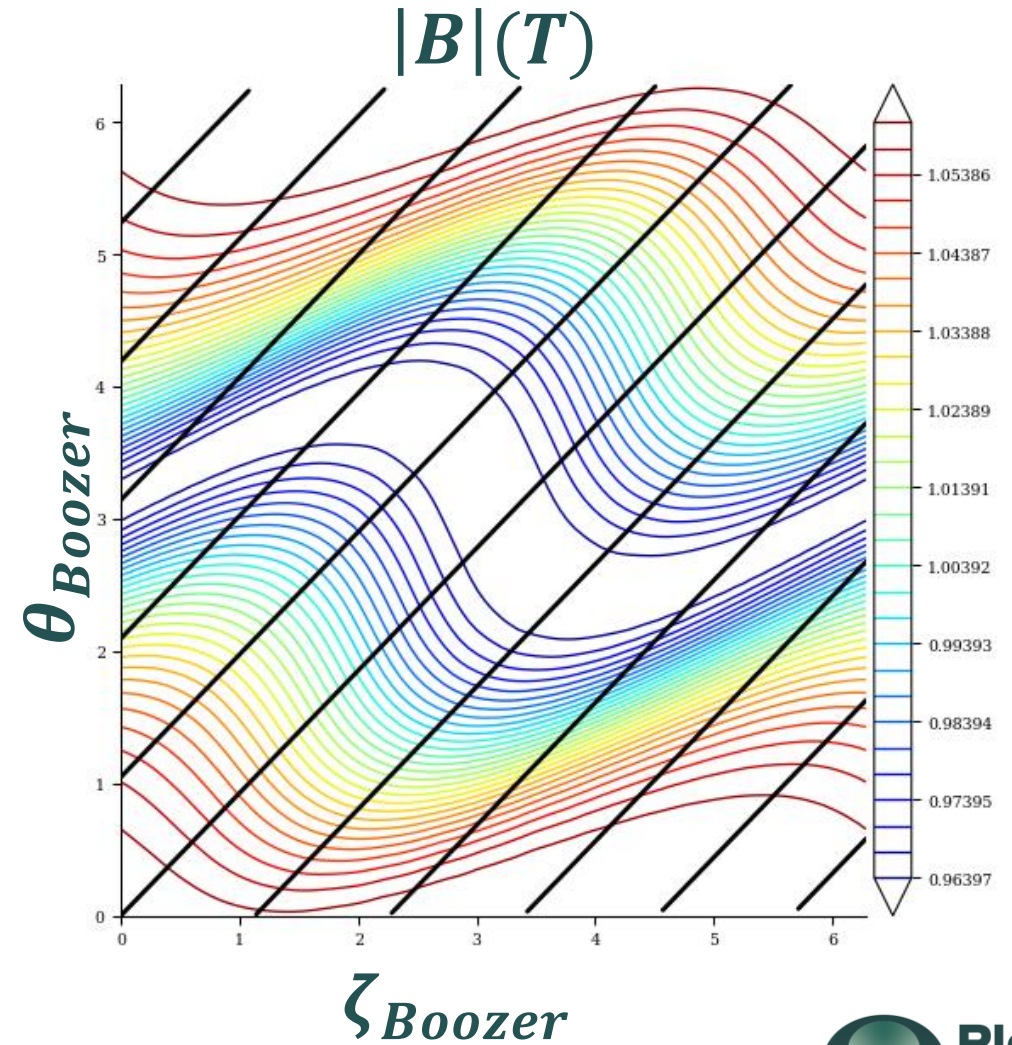
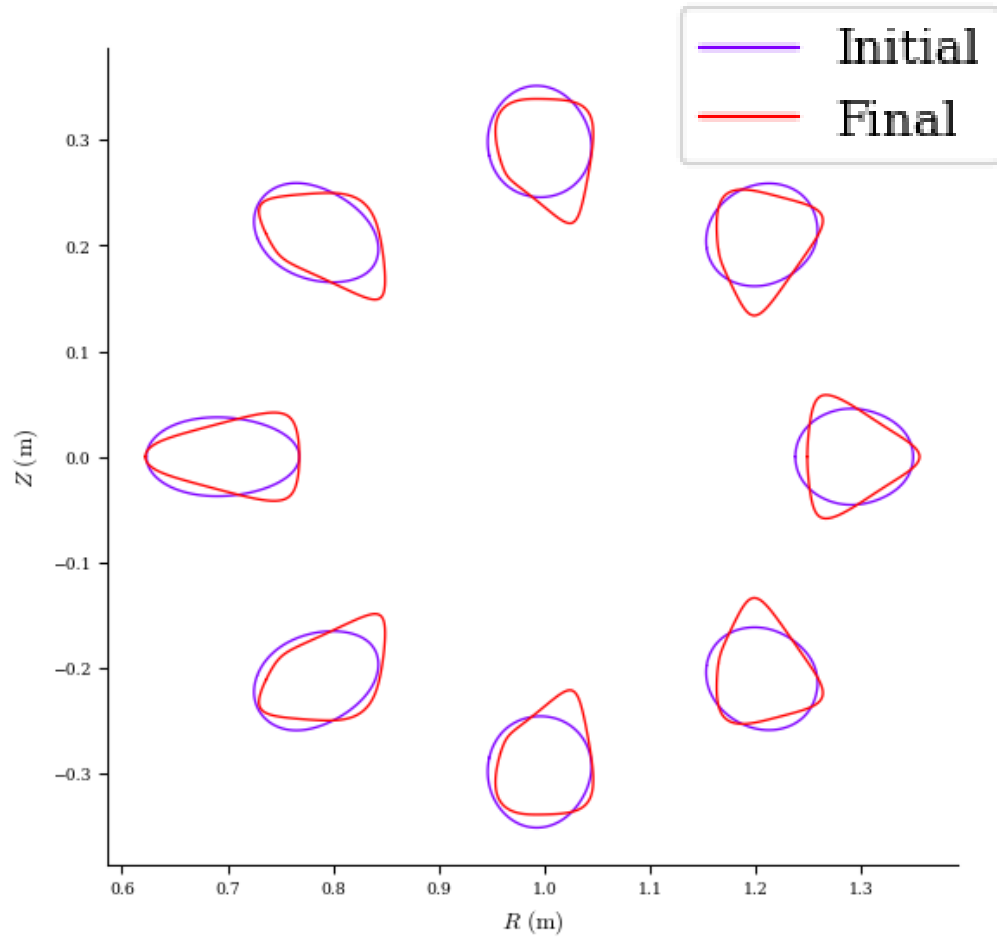
Initial equilibrium:

- QA NAE equilibrium from pyQSC
- Fixing axis and $O(\rho)$ of equilibrium

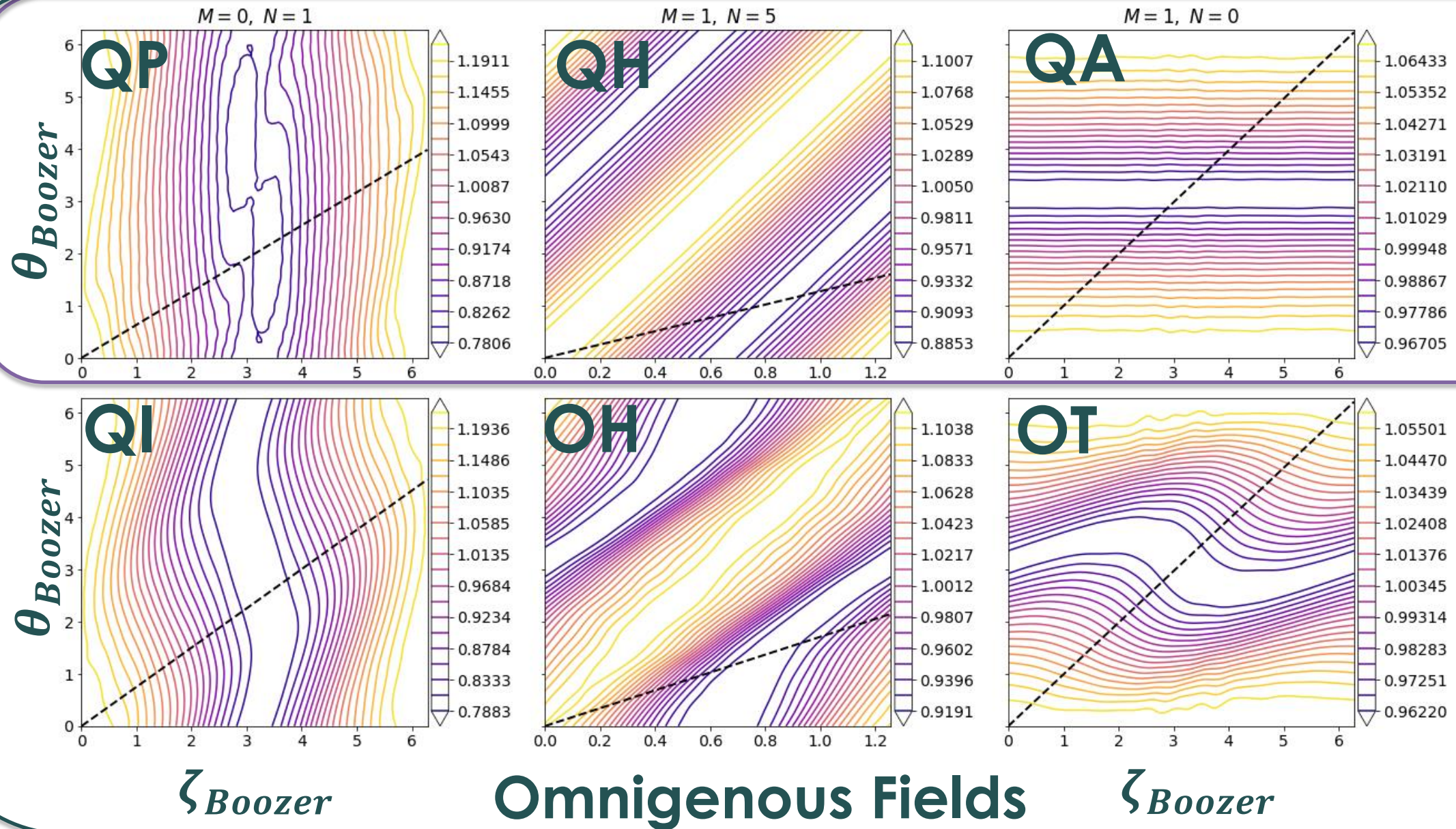
Optimization targets:

- Targeting specific omnigenous field with toroidally closed $|B|$ contours on multiple surfaces
- Force balance at finite beta

Example 2: Toroidally closed omnigenity



DESC can find equilibria with any omnigenity type



QS Fields

Constrained Optimization

Stellarator optimization is full of constraints

- **Geometry / Engineering:**

- Aspect Ratio = 6
- Minimum coil-plasma distance > 1.2m
- Maximum coil curvature < 0.6

- **Stability:**

- Equilibrium
- Magnetic Well > 0

- **Physics:**

- $I_{\text{edge}} = 5/5$
- $J_{\text{boot}} = 0$

- **Self Consistency:**

- $J_{\text{MHD}} = J_{\text{kinetic}}$
- $p_{\text{MHD}} = p_{\text{kinetic}}$
- $B_{n,\text{plasma}} = -B_{n,\text{coils}}$

$$\begin{array}{l} \min_x f(x) \\ \text{subject to } g_{\text{eq}}(x) = 0 \\ g_{\text{ineq}}(x) \geq 0 \end{array}$$

← Equality Constraints

← Inequality Constraints

Current methods : Sum of Squares + max

$$\min_x f(x) \text{ subject to } \begin{aligned} g_{eq}(x) &= 0 \\ g_{ineq}(x) &\geq 0 \end{aligned}$$

Combine all constraints into a single objective with different weights:

$$\min_x f(x) + w_1 [g_{eq}(x)]^2 + w_2 \max(0, g_{ineq}(x))^2$$

Limitations:

- **Hard to guess a-priori what weights should be**
- **Constraints are only satisfied as $w \rightarrow \text{infinity}$**
- **Leads to badly scaled problem**
- **Non-smooth due to max term**

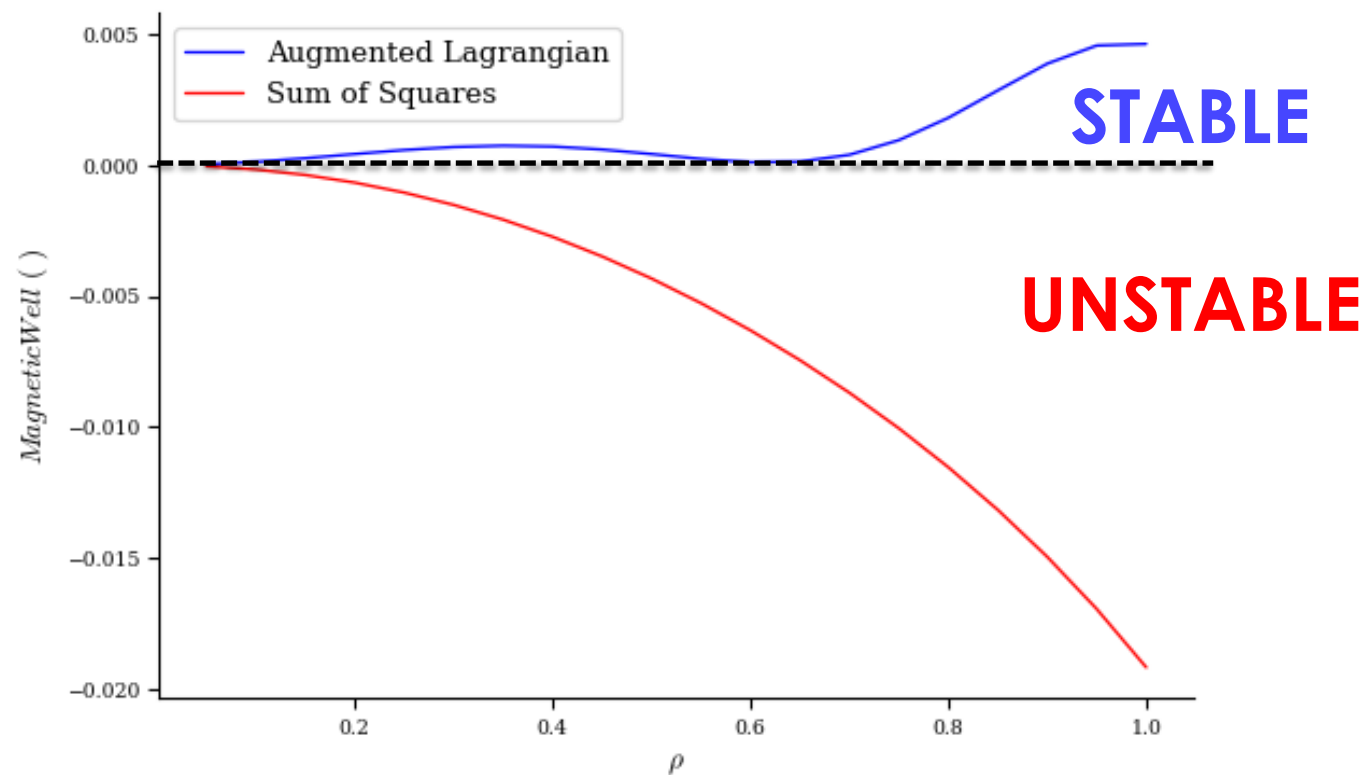
Combination of traditional Lagrangian + quadratic penalty

$$\mathcal{L}(x, \lambda, \mu) = f(x) + \lambda^T \mathbf{g}(x) + \mu g^2(x)$$

- **Smooth function**
- **Systematic way exists to increase penalty -> remove guesswork of weights!**
- **Python/JAX version implemented in DESC**

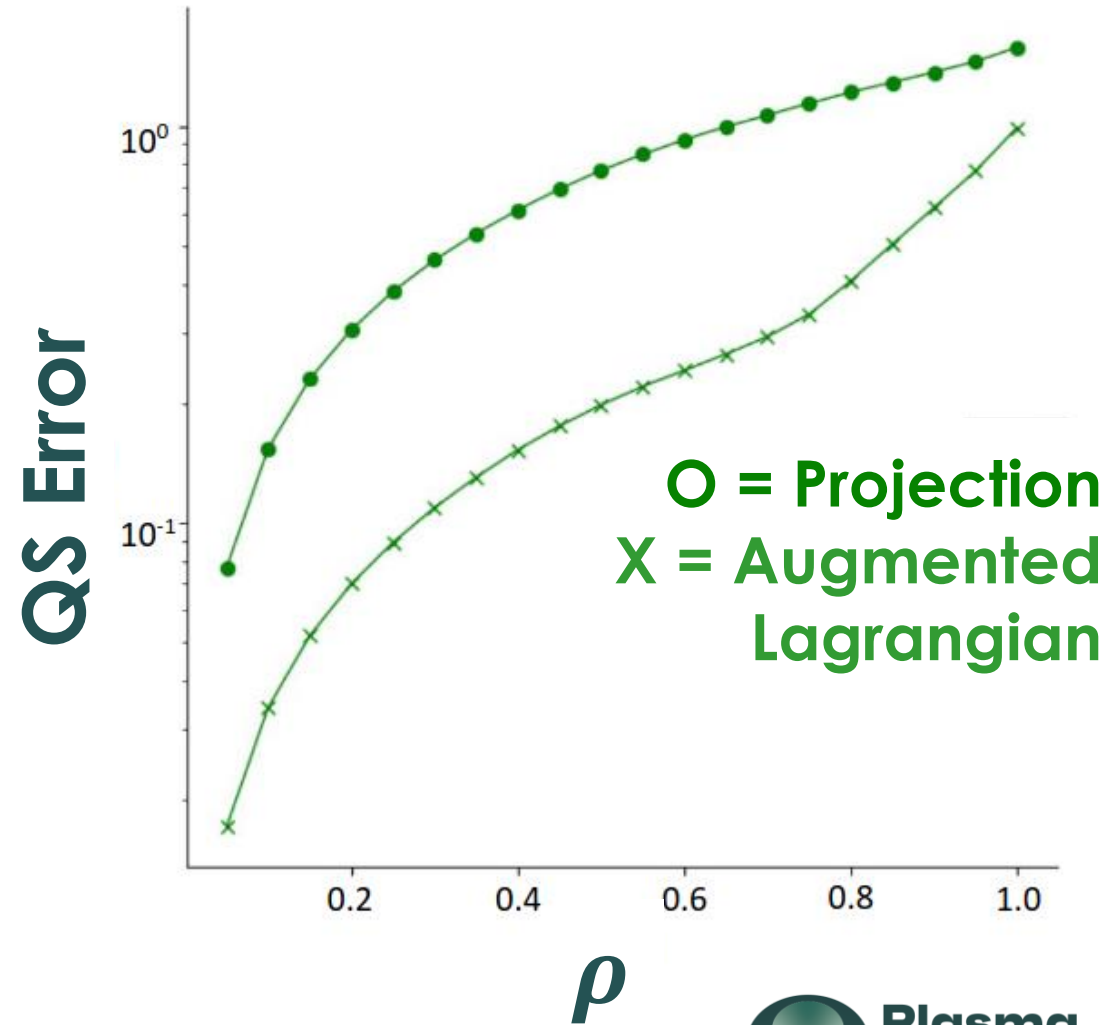
Augmented Lagrangian takes guesswork out of penalty terms

- **Simple quadratic penalty fails to give stable equilibrium, even for large values of weight**
- **Instead applying inequality constraint w/ augmented Lagrangian gives magnetic well > 0**



Augmented Lagrangian approach allows better solutions to be found

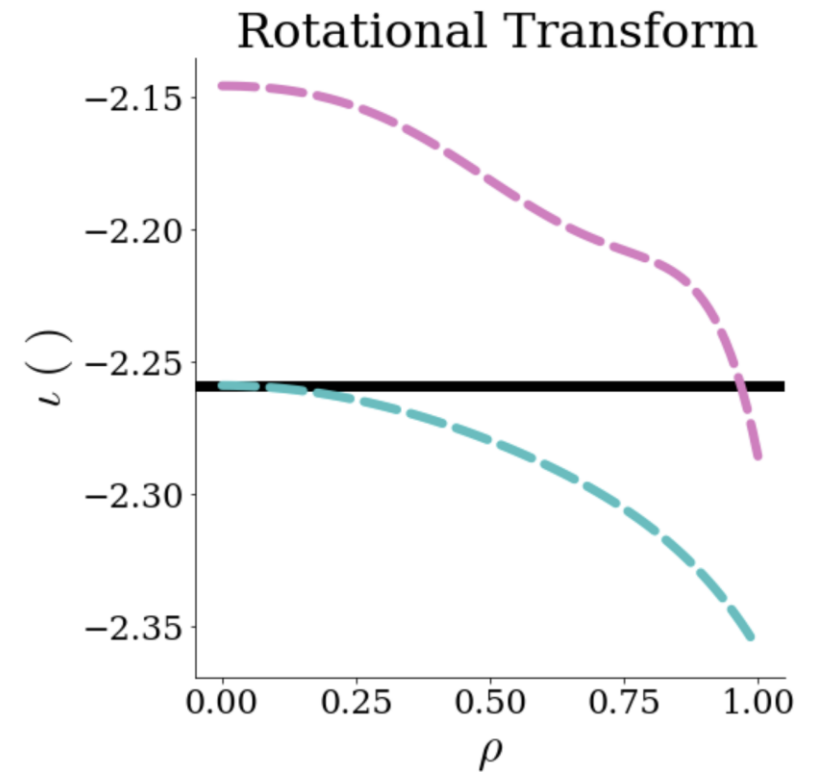
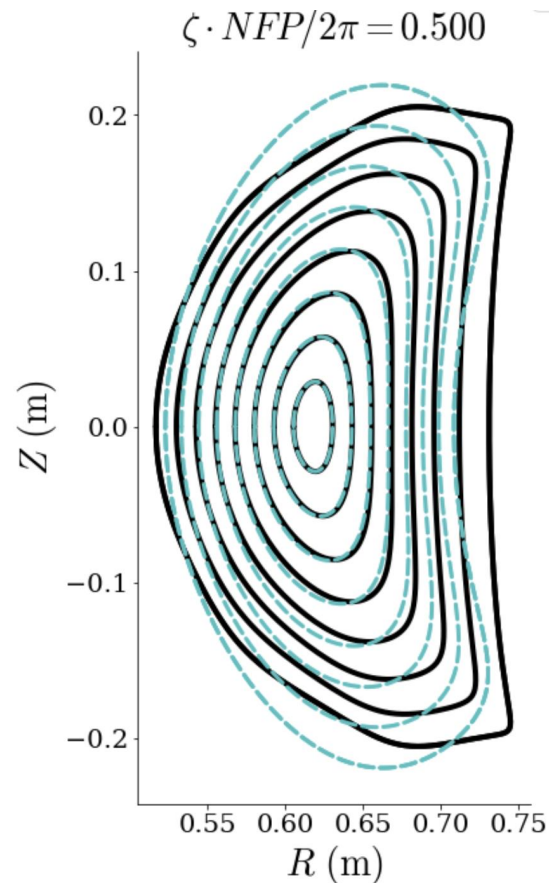
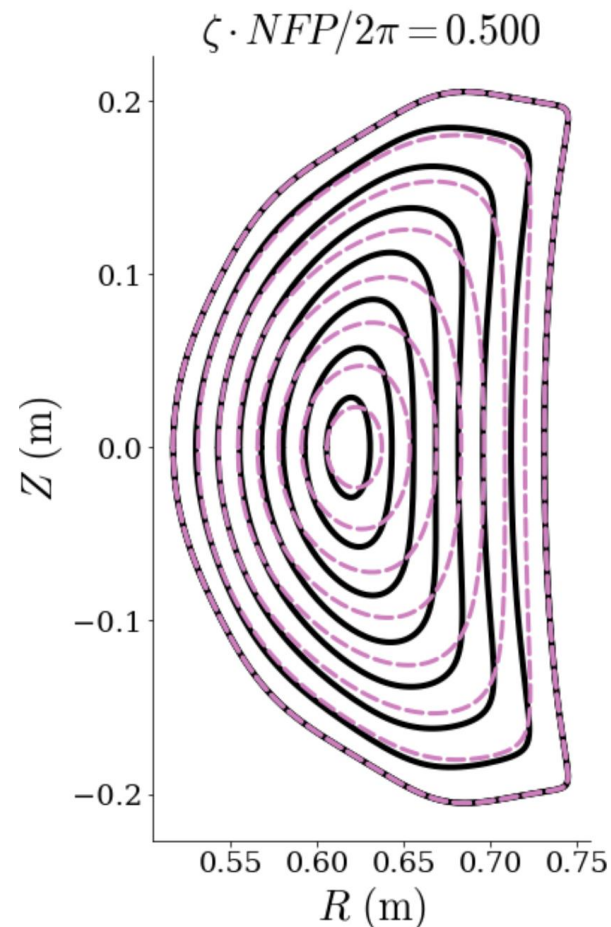
- **Conventional projection method re-solves from boundary at each step, to enforce force balance**
- **Augmented Lagrangian systematically varies weighting of constraints vs objective to improve QS**
 - **Allows it to achieve better final result, without need for guesswork**



Summary

DESC Offers Unique Approaches to Stellarator Optimization

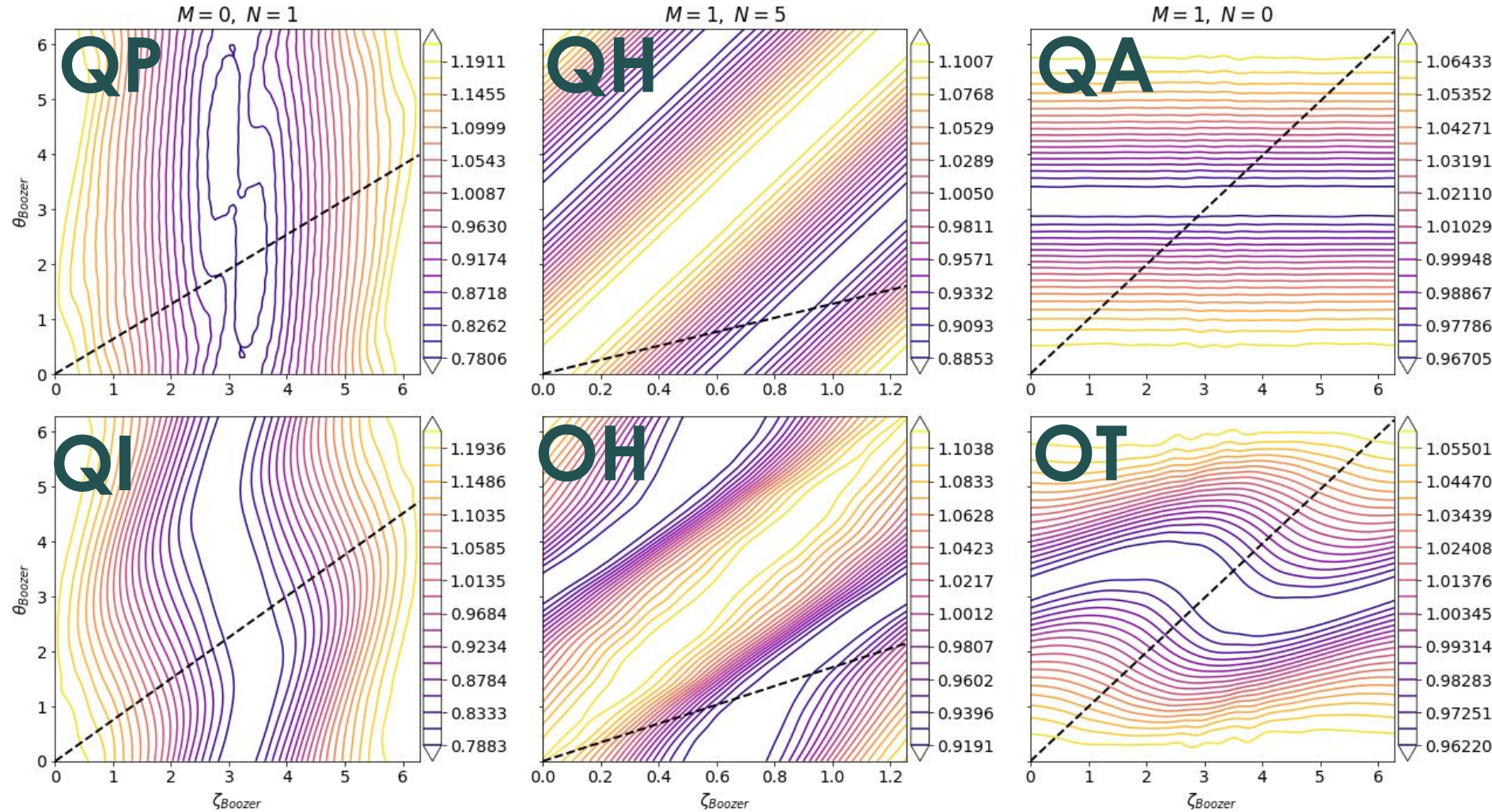
Poincare and NAE-Constrained Equilibria offer **new ways to explore phase space of nested surface stellarators**



- NAE Surfaces
- - - DESC NAE constrained
- - - DESC Fixed Surface

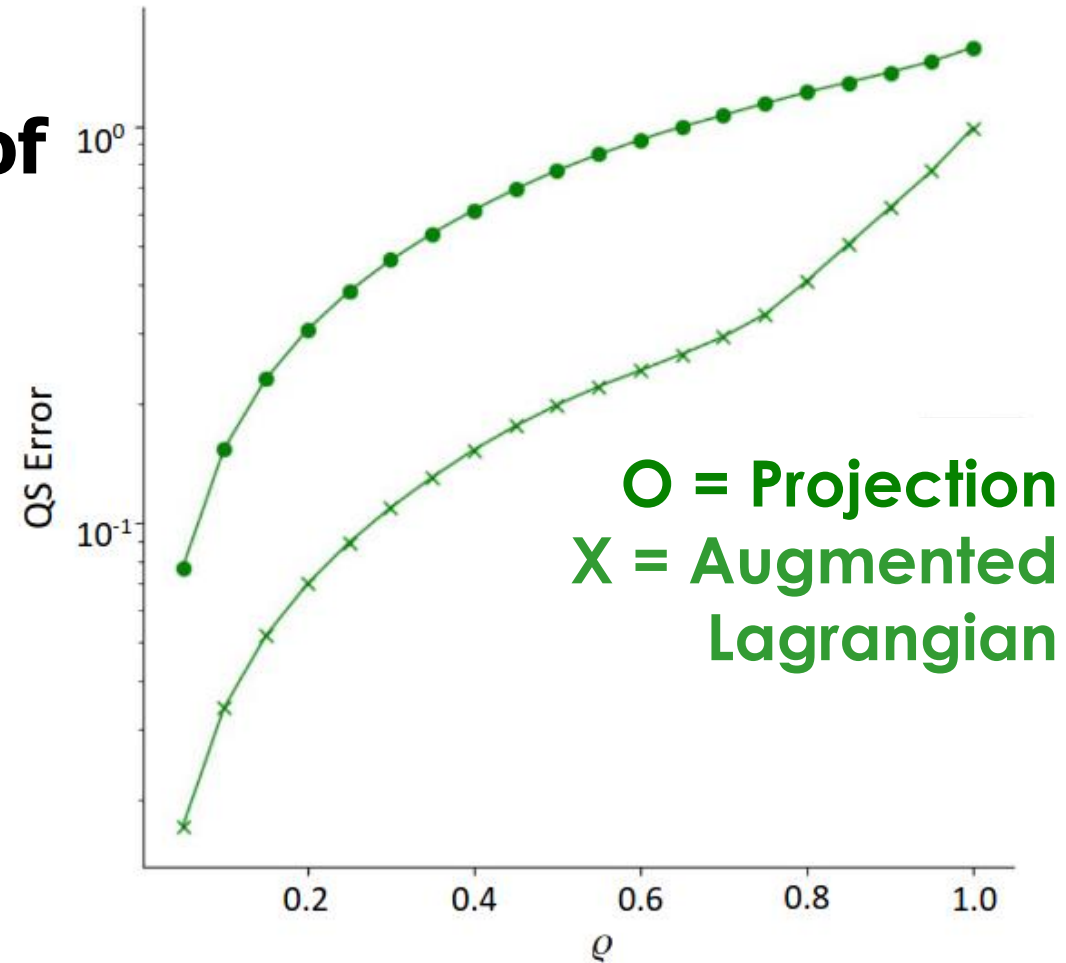
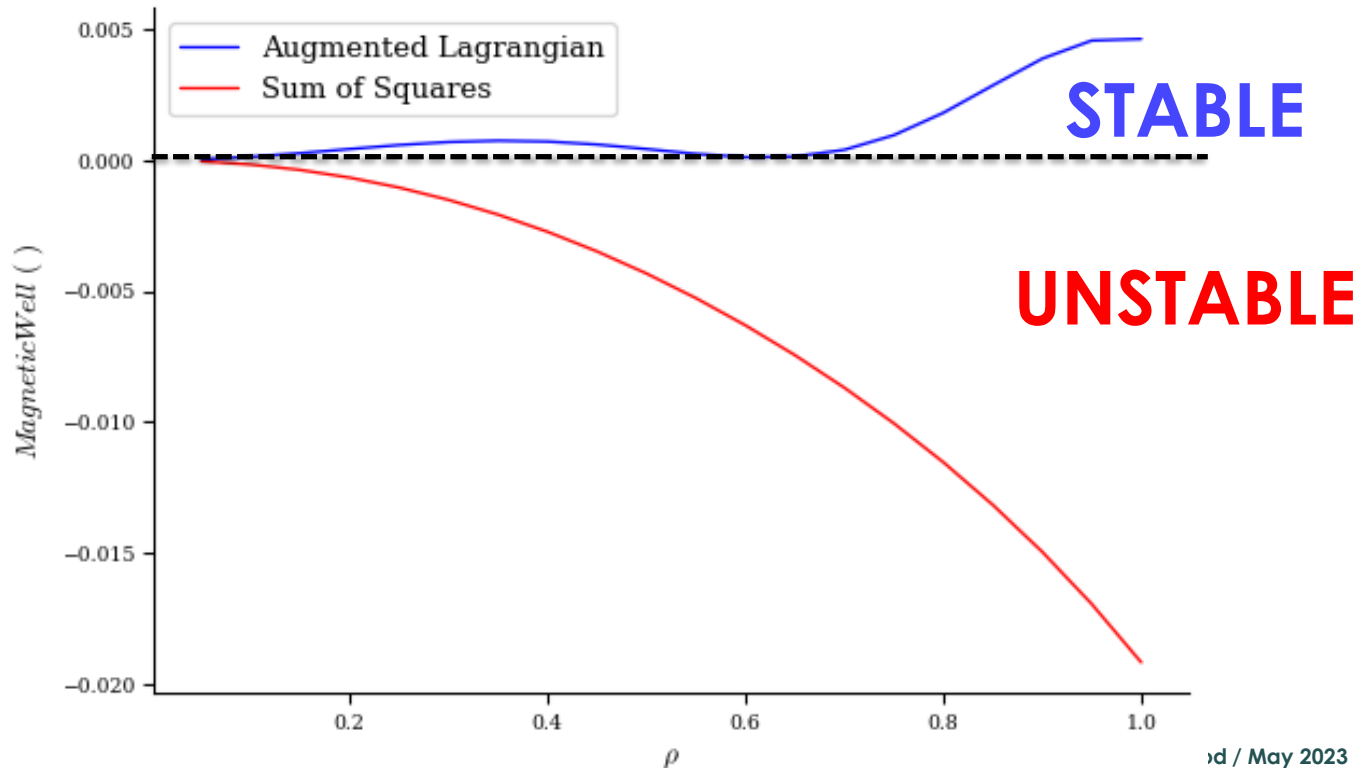
DESC Offers Unique Approaches to Stellarator Optimization

Omnigenous field phase space model allows **systematic exploration of the space of omnigenous stellarators**



DESC Offers Unique Approaches to Stellarator Optimization

- Proper Constrained Optimization in DESC can **obtain better solutions and eliminates the need for guesswork of penalty terms**



Software

- **Open-source repository:** <https://github.com/PlasmaControl/DESC>
- **Python package:** `pip install desc-opt`

Papers

- **The DESC Stellarator Code Suite Part I** <https://arxiv.org/abs/2203.17173>
- **The DESC Stellarator Code Suite Part II** <https://arxiv.org/abs/2203.15927>
- **The DESC Stellarator Code Suite Part III** <https://arxiv.org/abs/2204.00078>

The Plasma Control group is recruiting graduate students and post-docs!

Contact Egemen Kolemen: ekolemen@pppl.gov